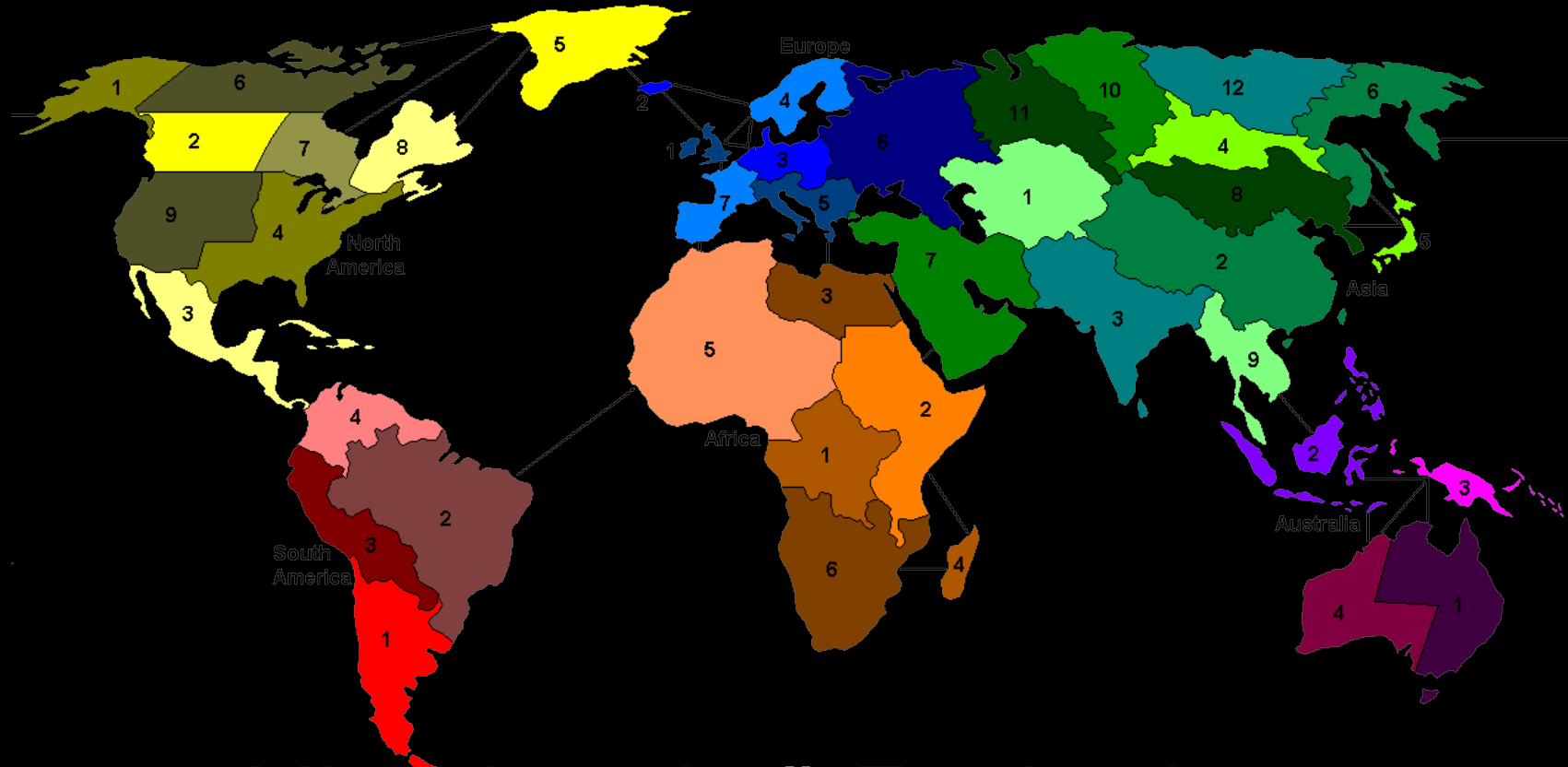


# Lecture 3: Dynamic fault trees



Milan Lopuhaä-Zwakenberg

Formal Methods & Tools

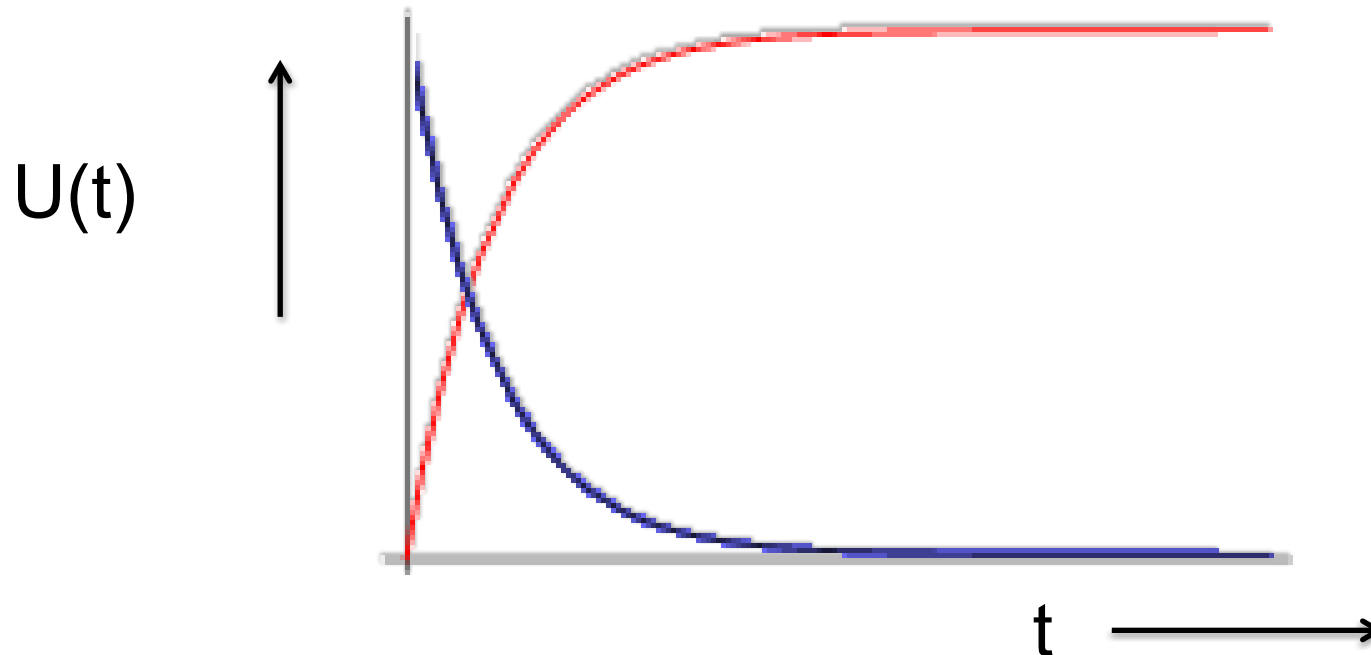
# System (un)reliability

- Unreliability

$$U(t) = \mathbf{P}[\text{failure before time } t]$$

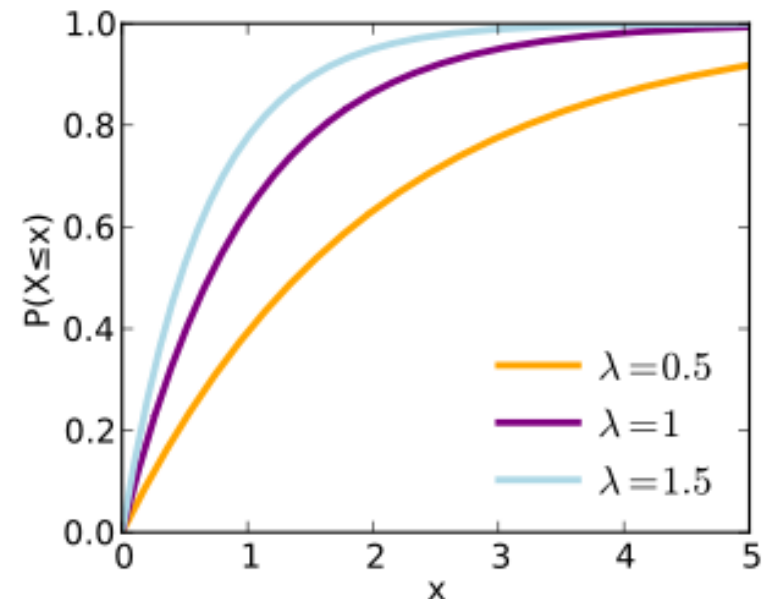
- Reliability / Survivor function

$$\begin{aligned} R(t) &= \mathbf{P}[\text{no failure until time } t] \\ &= 1 - U(t) \end{aligned}$$



# Exponential distribution: cumulative density function

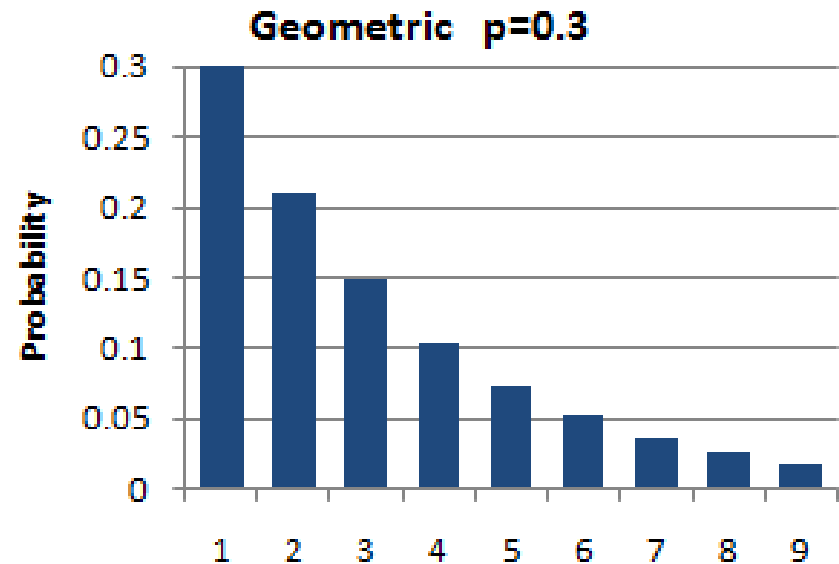
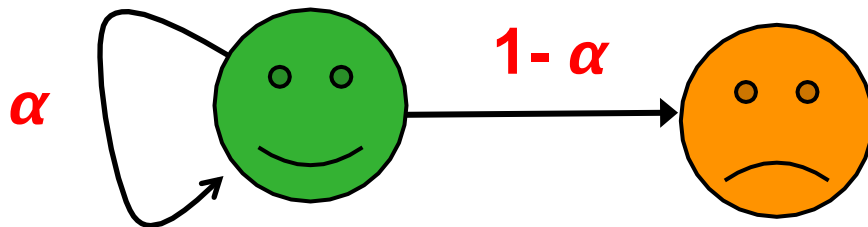
- Unreliability, CDF
  - $\mathbf{P}[\text{fail before } t] = \mathbf{P}[X \leq t] = 1 - e^{-\lambda t}$
  - $X$ : random variable denoting failure time
- Parameter:  $\lambda$ 
  - Failure rate,  $\lambda > 0$
  - $\lambda =$  expected number of fails per time unit
  - $\mathbf{E}[X] = 1/\lambda$
- Reliability / survivors function, CDF
  - $\mathbf{P}[\text{fail after } t] =$ 
    - $= 1 - \mathbf{P}[\text{fail before } t]$
    - $= 1 - (1 - e^{-\lambda t})$
    - $= e^{-\lambda t}$
    - $= (e^{-\lambda})^t$  {write  $e^{-\lambda} = \alpha$ }
    - $= \alpha^t$



# Exponential distribution: cumulative density function

## Reliability / survivors function, CDF

- $\mathbf{P}[\text{fail after } t] = \mathbf{P}[X > t] = \alpha^t$
- “Survive” each time unit with probability  $\alpha$ 
  - $t=0: \alpha^0 = 1$
  - $t=1: \alpha$
  - $t=2: \alpha^2$
  - $t=3: \alpha^3$
  - ...
  - $t=1/2: \alpha^{1/2}$
  - $t=14.7302: \alpha^{14.7302}$



Note: picture displays the discrete version, for fixed time steps

# Exponential distribution: **memoryless**

- **Memoryless**

- Makes this distribution easier
- Crucial for use in transition systems

- $\mathbf{P}[X > t + s \mid X > s] = \mathbf{P}[X > t]$

*No matter how long you have already been operational,*

*the probability that remain for operational for  $t$  more time units is always  $\mathbf{P}[X > t]$*

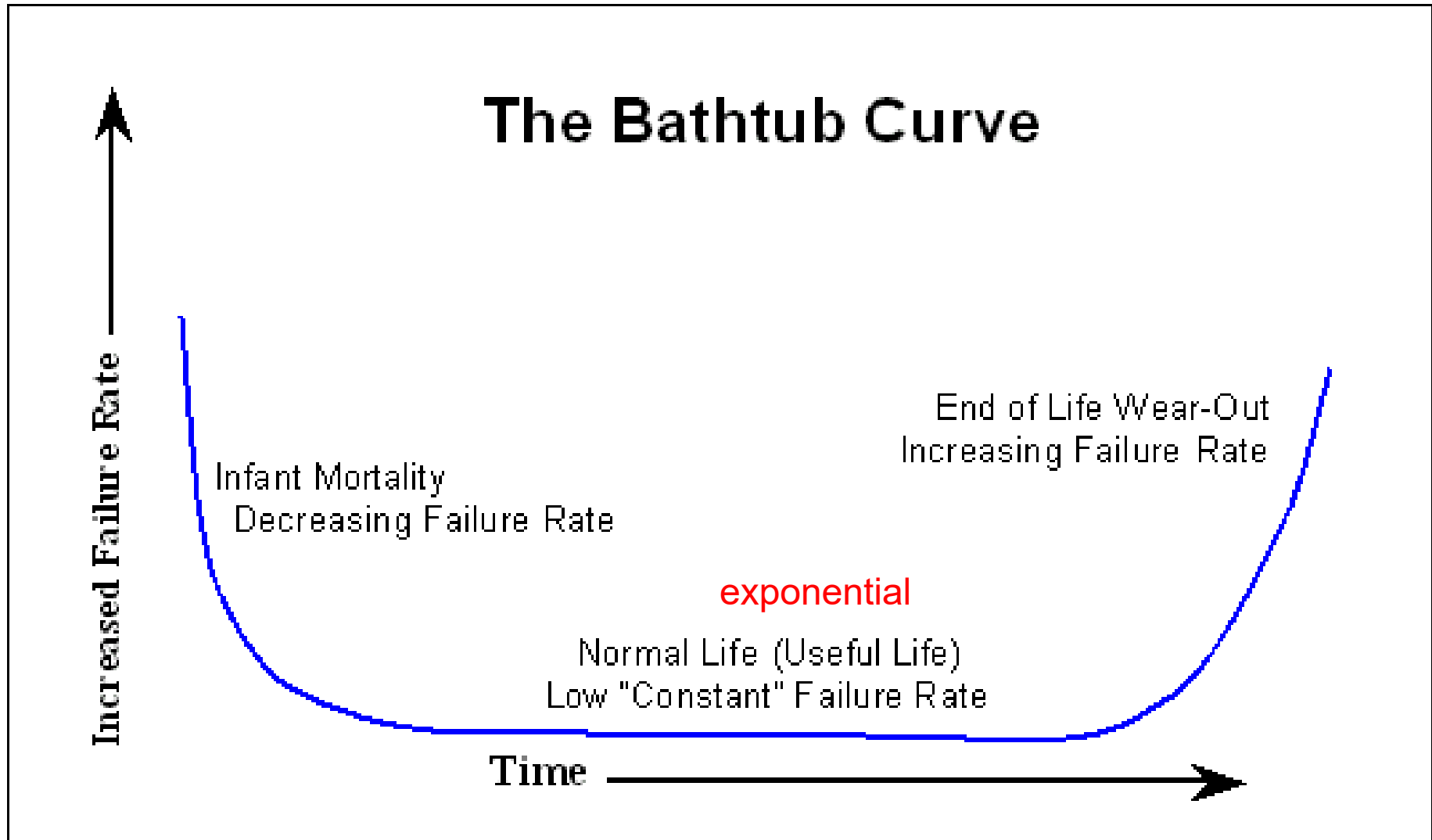
$$\underbrace{\mathbf{P}[X > t+s \mid X > s]} = \underbrace{\mathbf{P}[X > t]}$$

Given that you were operational for  $s$  time units,  
remain operational for at least  $t + s$  most units

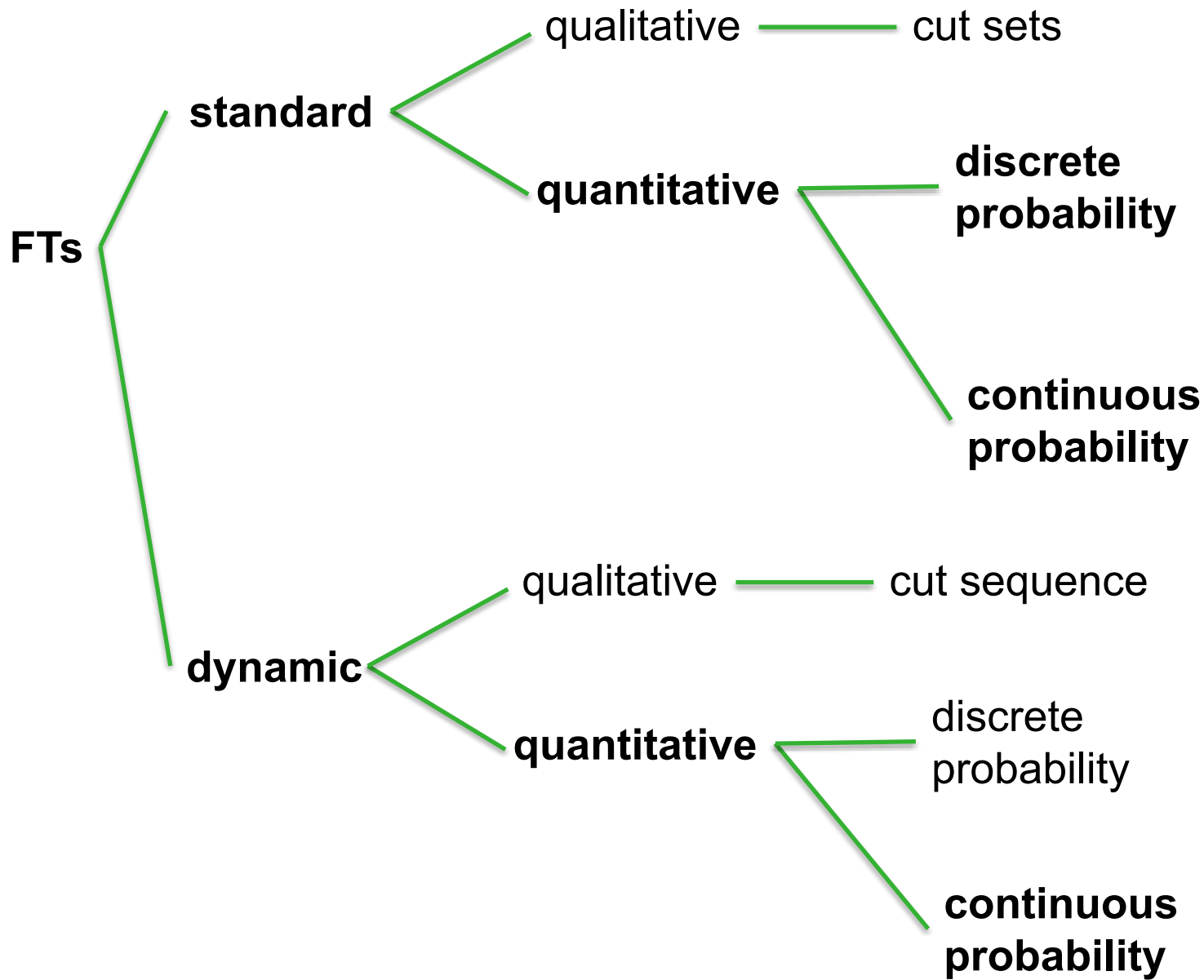
= you must remain operational  
for at least  $t$  more time units

Remain operational for  $t$  more time units  
Independent of  $s$

# Bath tub curve: degradation behaviour of systems



# Overview



## Technique

- Recursive
- BDDs

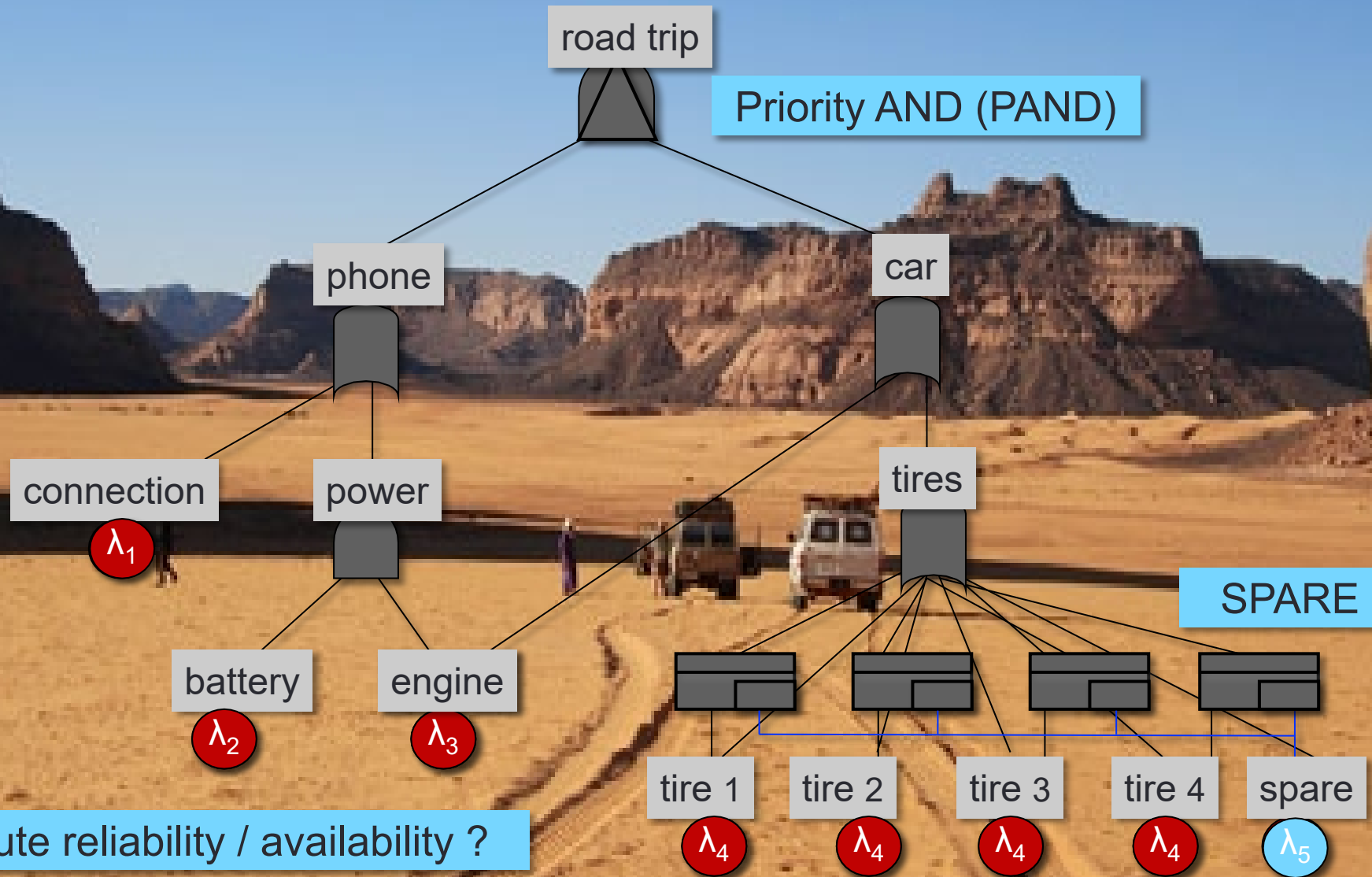
## Technique

- Bottom up
- Cut sets
- BDDs

## Today

- Composition
- Minimization
- Exponentials

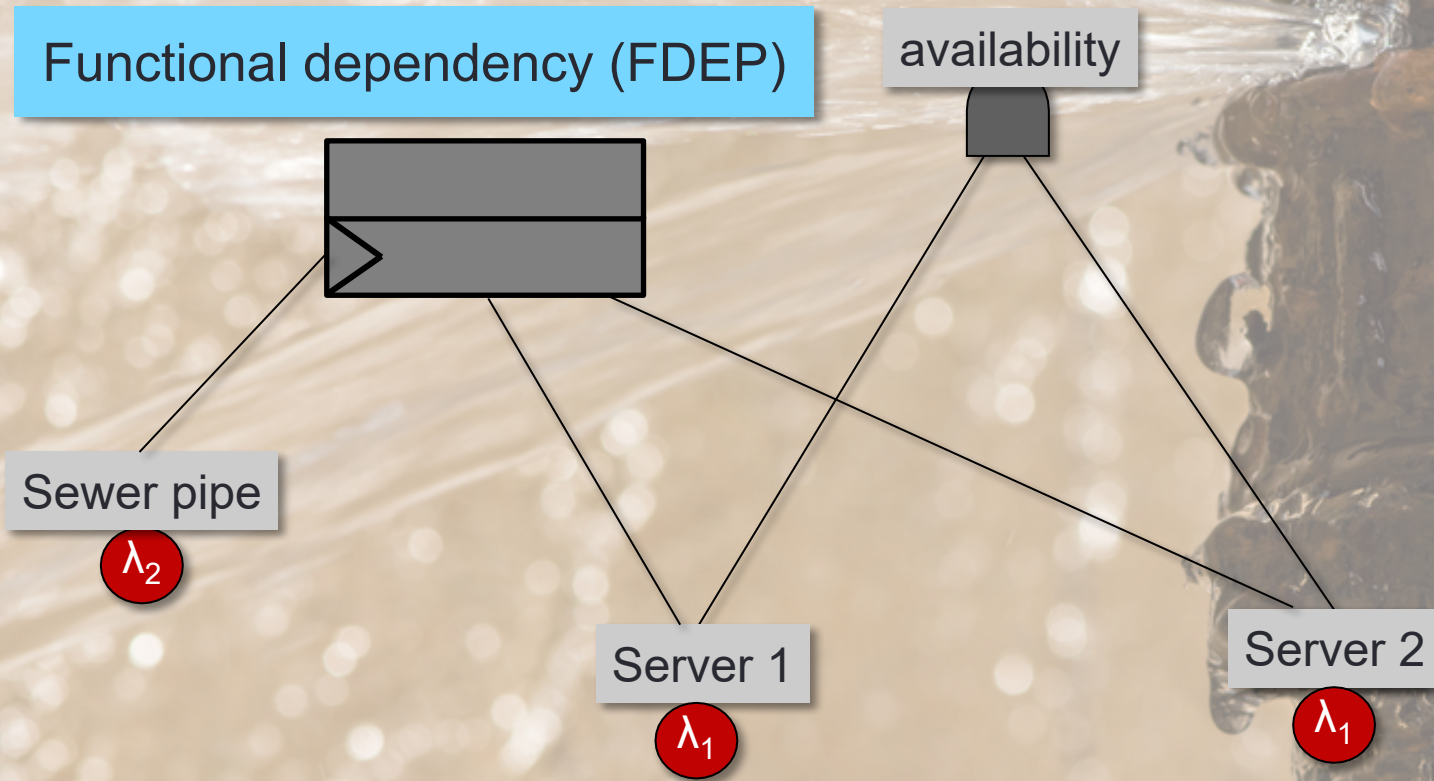
# Example: Safe road trip



Compute reliability / availability ?

Lower failure rate for inactive spare

# Example: server room



# Dynamic Fault Tree (DFT)

## Definition

- Fault tree + PAND, SPARE, FDEP gates

## Qualitative analysis

- *Cut sequence* instead of *cut set*
- (*connection, spare, tire 1*) is a cut sequence
- (*spare, tire 1, connection*) is not
- (*battery, engine*) might be, depending on your definition

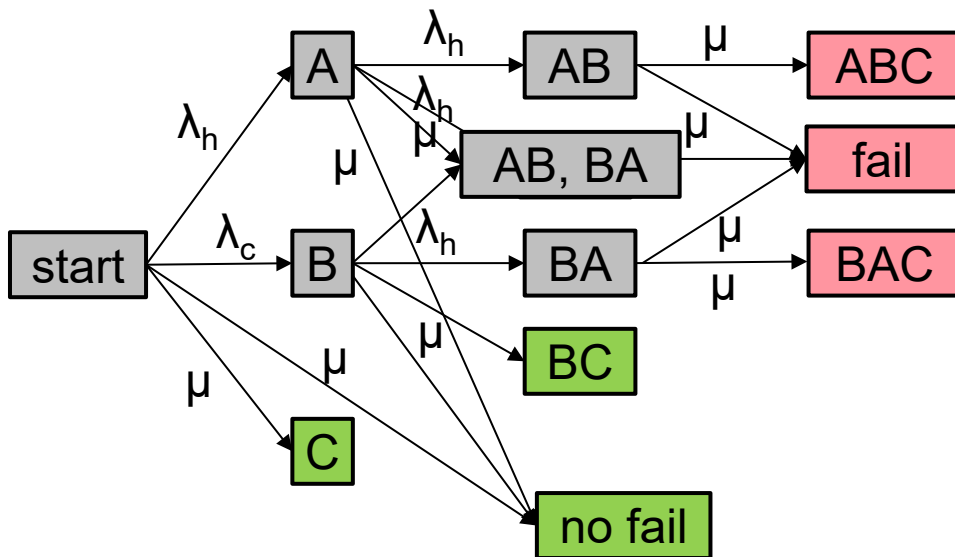
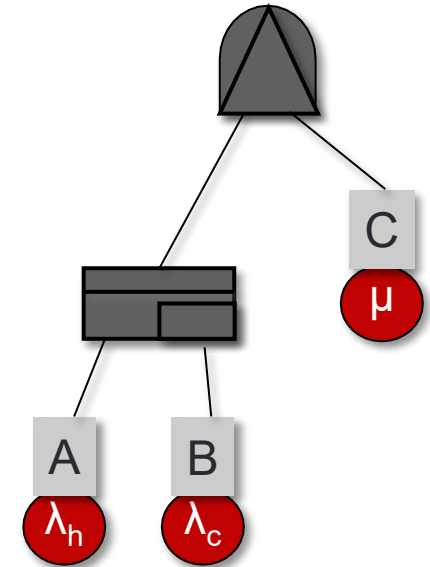
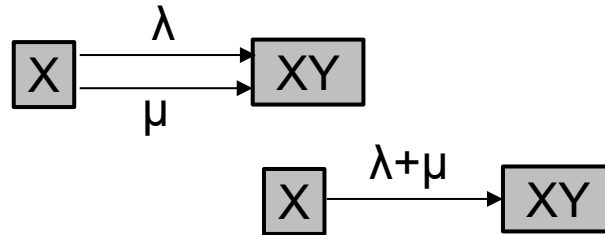
## Quantitative analysis

- What is  $U(t)$  = failure probability at time  $t$ ?
- BDDs do not work!

# Quantitative DFT analysis

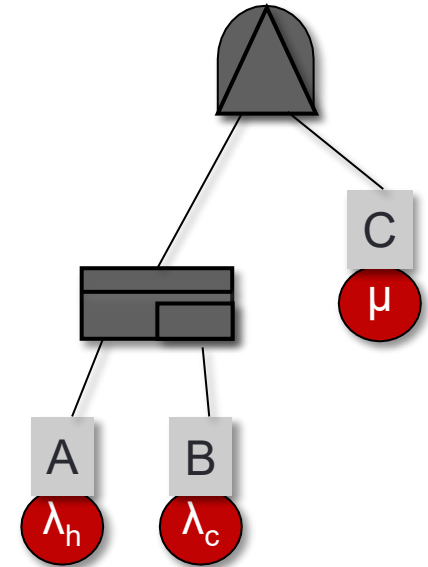
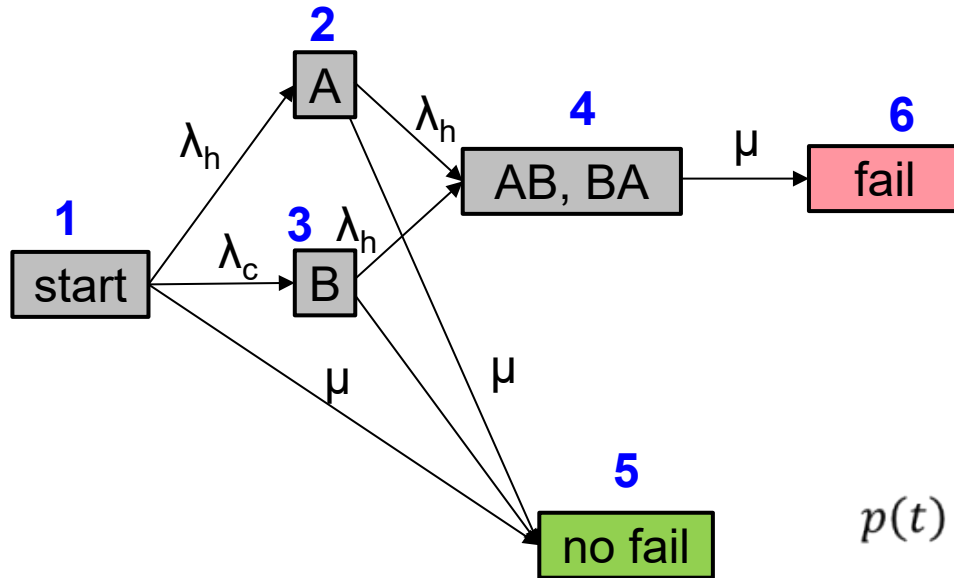
1. Create (continuous) Markov chain
2. Simplify

1. Merge fails, no fails, equivalent states
2. Merge double edges
3. Eliminate self-loops



# Quantitative DFT analysis

1. Create (continuous) Markov chain
2. Simplify
3. Derive transition matrix
4. Compute probability vector



$p(t)$  = probability vector of system state at time  $t$

$$A = \begin{pmatrix} -\lambda_h - \lambda_c - \mu & \lambda_h & \lambda_c & 0 & \mu & 0 \\ 0 & -\lambda_h - \mu & 0 & \lambda_h & \mu & 0 \\ 0 & 0 & -\lambda_h - \mu & \lambda_h & \mu & 0 \\ 0 & 0 & 0 & -\mu & 0 & \mu \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

$$p(0) = (1 \ 0 \ 0 \ 0 \ 0 \ 0)$$

$$p(t) = p(0) \cdot e^{tA}$$

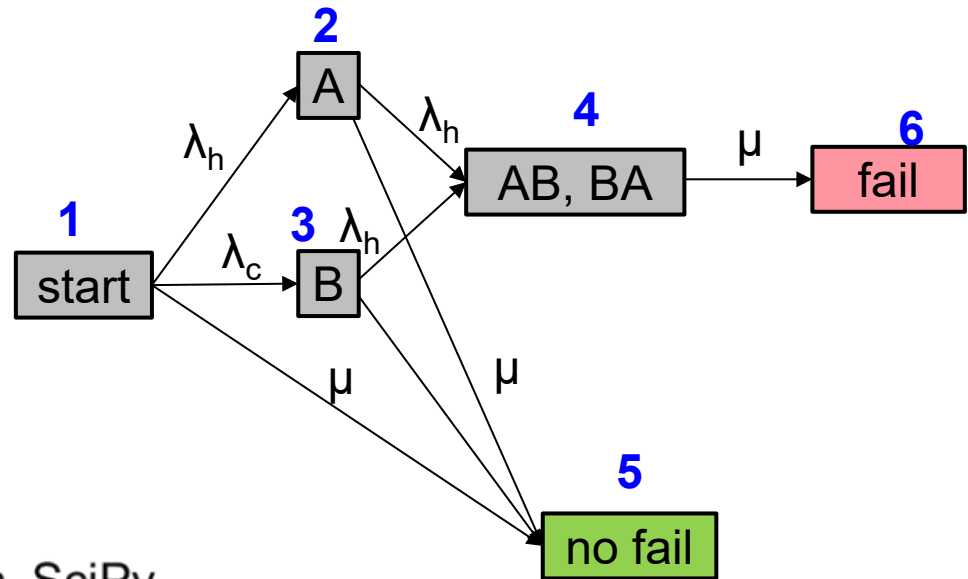
# Quantitative DFT analysis

1. Create (continuous) Markov chain
2. Simplify
3. Derive transition matrix
4. Compute probability vector

$$p(t) = p(0) \cdot e^{tA}$$

$$e^X = \sum_{k=0}^{\infty} \frac{1}{k!} X^k$$

- Can be computed with Wolfram alpha, SciPy,...
- Google "Matrix exponential"
- $t$  integer:  $p(t) = p(0) \cdot M^t$  with  $M = e^A$



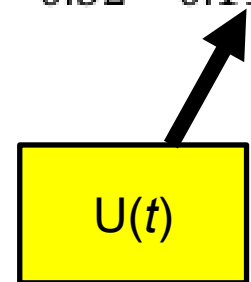
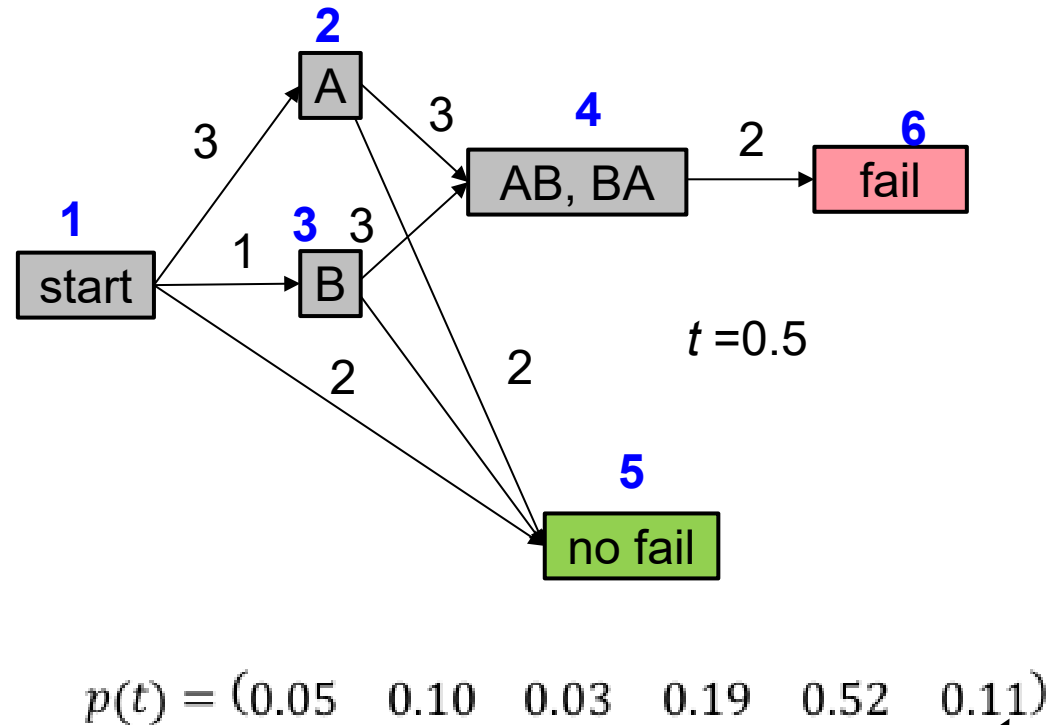
# Quantitative DFT analysis

1. Create (continuous) Markov chain
2. Simplify
3. Derive transition matrix
4. Compute probability vector

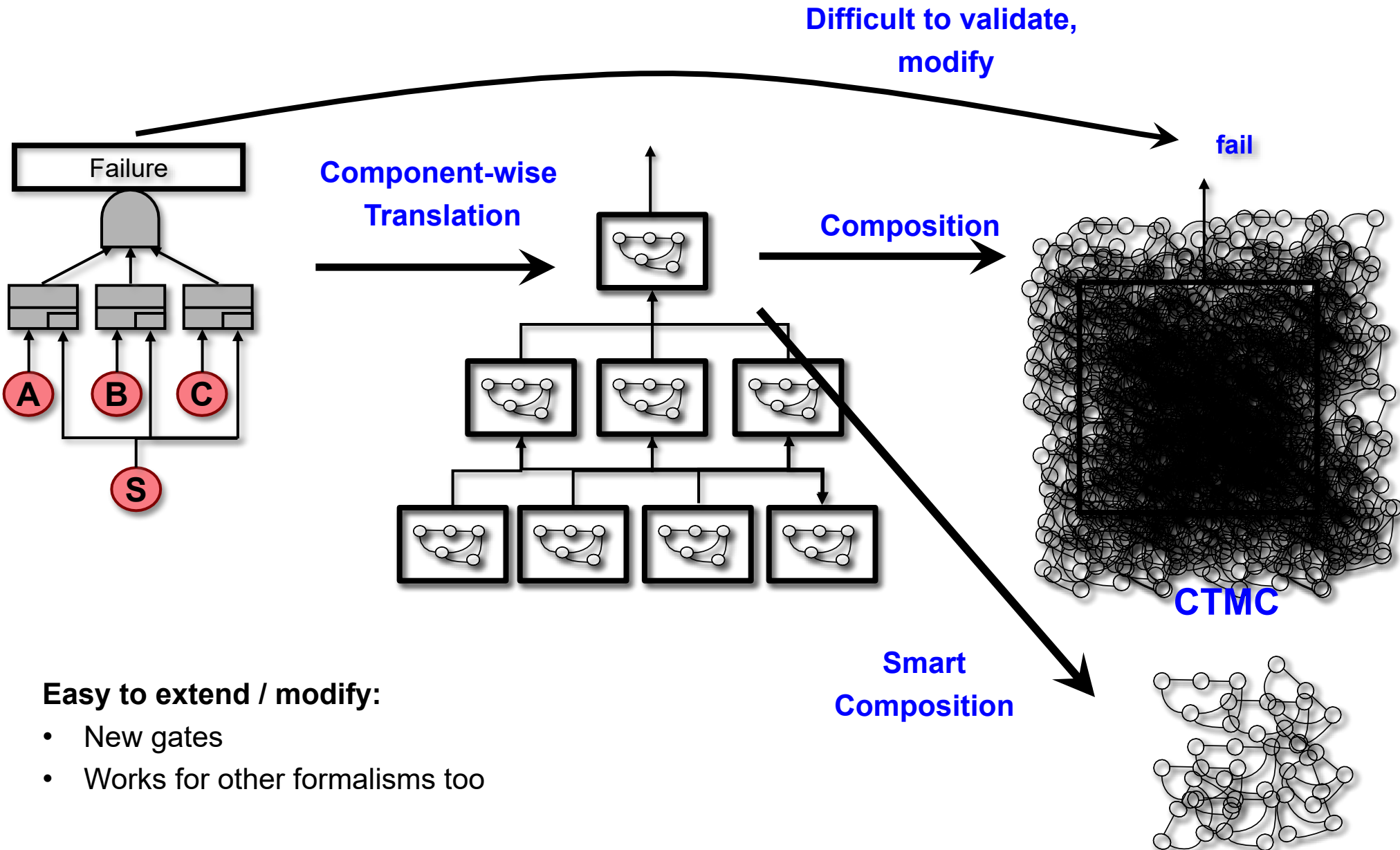
$$p(t) = p(0) \cdot e^{tA}$$

$$tA = \begin{pmatrix} -3 & 1.5 & 0.5 & 0 & 1 & 0 \\ 0 & -2.5 & 0 & 1.5 & 1 & 0 \\ 0 & 0 & -2.5 & 1.5 & 1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\exp(tA) = \begin{pmatrix} 0.05 & 0.10 & 0.03 & 0.19 & 0.52 & 0.11 \\ 0 & 0.08 & 0 & 0.29 & 0.37 & 0.26 \\ 0 & 0 & 0.08 & 0.29 & 0.37 & 0.26 \\ 0 & 0 & 0 & 0.37 & 0 & 0.63 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

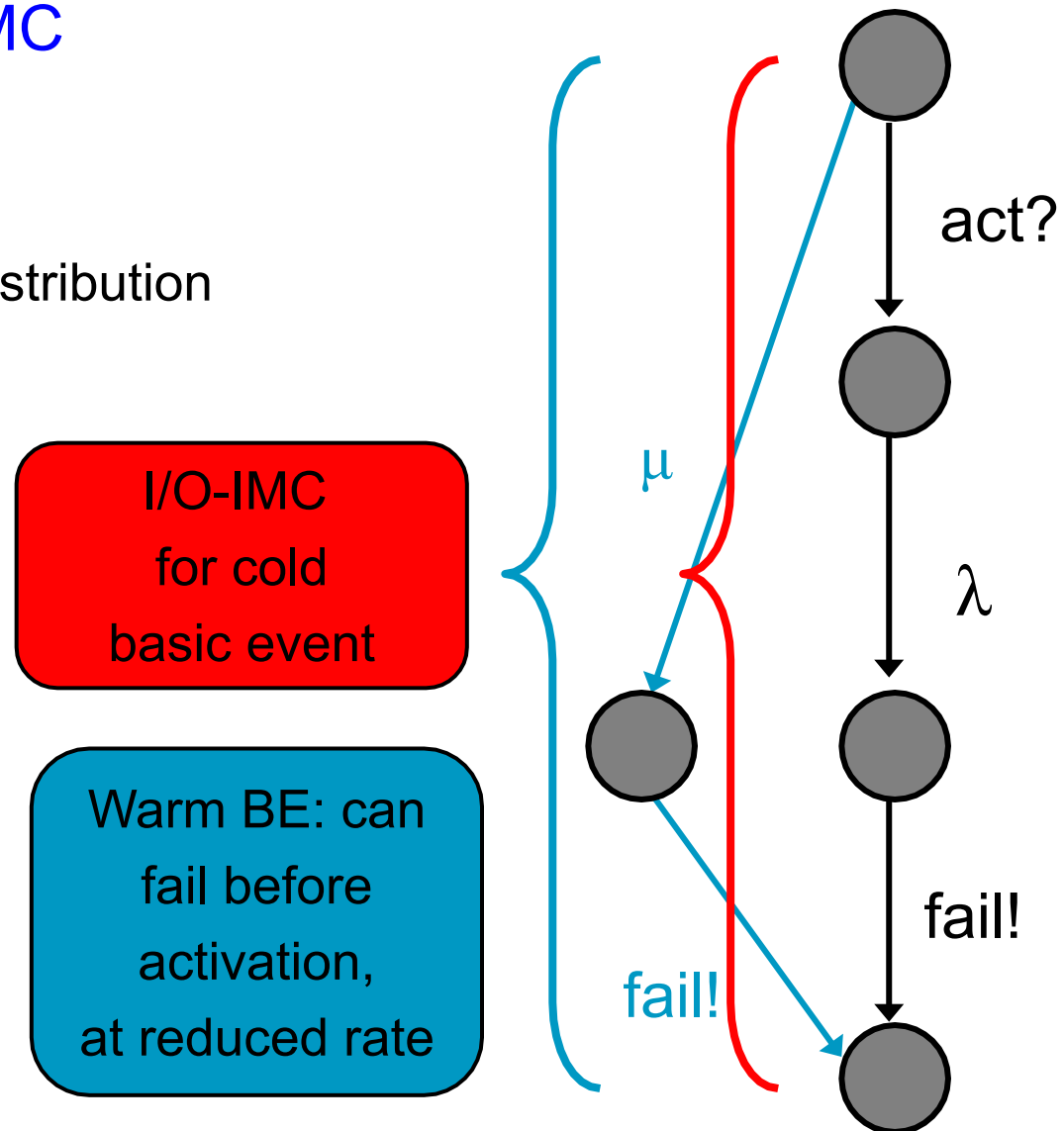


# Fault tree analysis via deep compositionality



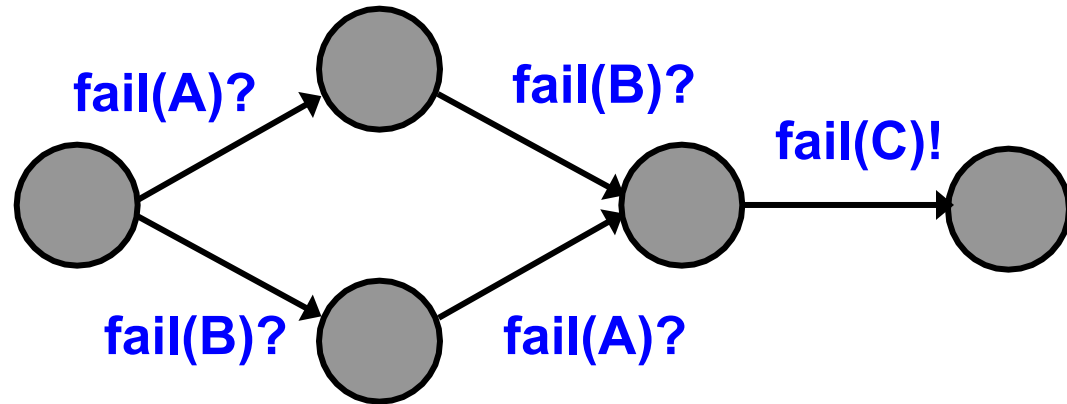
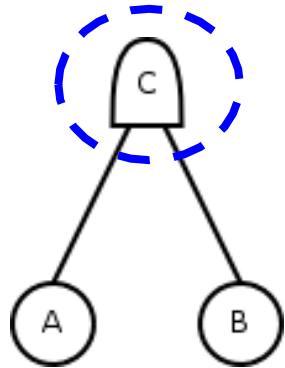
# Interactive Markov Chains (I/O-IMC)

- Transition systems + I/O + CTMC
- Markovian transitions (CTMC)
  - labeled with rates  $\lambda$
  - delays governed by exponential distribution
  - $P[\text{transition within } t \text{ sec}] = 1 - e^{-\lambda t}$
- Interactive transitions (I/O)
  - labeled with actions
  - synchronization
- Action signature
  - ? - Input actions: *delayable*
  - ! - Output actions: *immediate*
  - ; - Internal actions: *immediate*

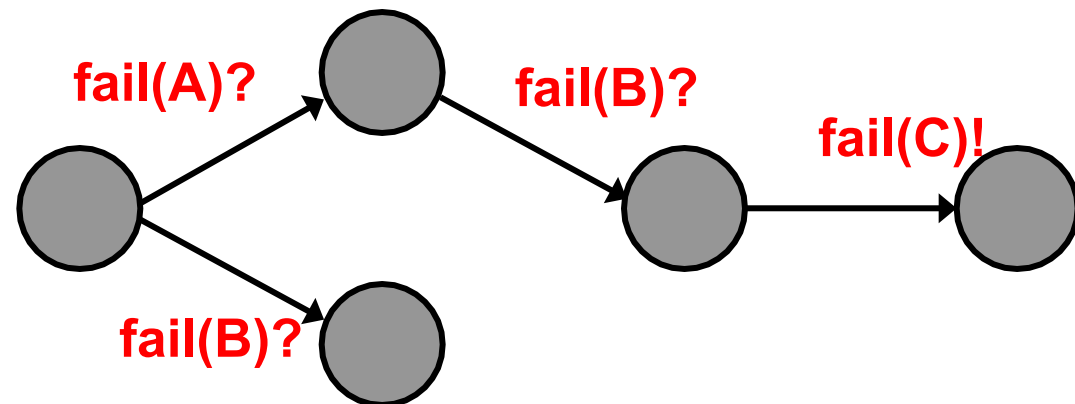
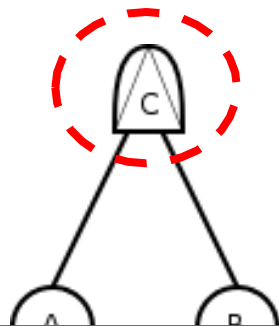


# Semantics for FT gates

## AND gate



## PAND gate



Similar, but more complex for other gates

# Conclusion

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## Dynamic fault trees

- More detailed modelling
- More complicated analysis
  - Qualitative: cut sequences
  - Quantitative: Markov Chains

## Next week:

- Monday: deadline homework 3, RA group project
- Wednesday, Friday: lectures on Testing