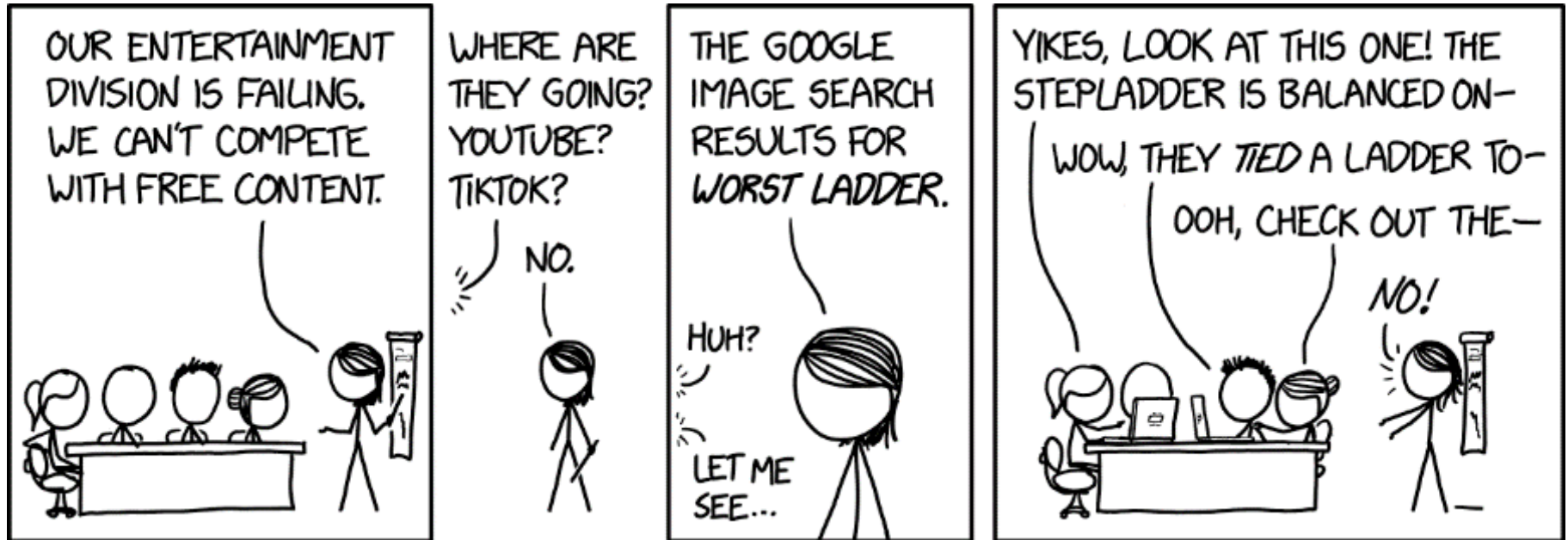


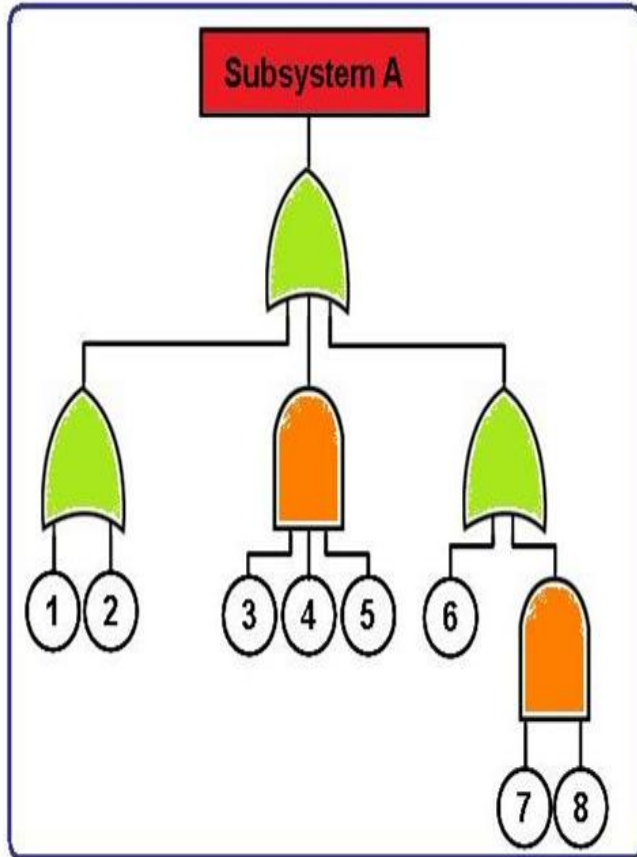
# Lecture 2: Fault Tree Analysis



Milan Lopuhaä-Zwakenberg  
Formal Methods & Tools

1. Risk = *effect of uncertainty on objectives*
2. Risk matrix
3. Mitigation strategies
4. Risk models: brainstorming + structured analysis
5. FMEA:
  1. Find many risks
  2. Prioritize them

# Fault trees



- *Graphical model*
  - Why does the system fail?
  - Decompose complex risks
- *Qualitative analysis*
  - Root causes, critical components
- *Quantitative analysis*
  - Reliability analysis
  - Time-dependence

Industrial tools: IsoGraph, RiskSpectrum

# FTA on Twitter

- Falcon 7 rocked, SpaceX
- Led by Elon Musk, Tesla
- Ready for launch June 2015



Elon Musk @elonmusk · Jun 28

That's all we can say with confidence right now. Will have more to say following a thorough **fault tree analysis**.

↩️ ↻️ 1.3K ⭐ 1.9K 👤 ⋮

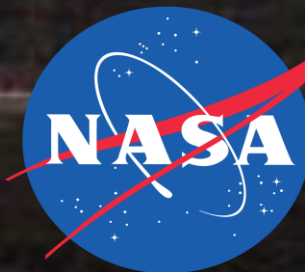
[View conversation](#)



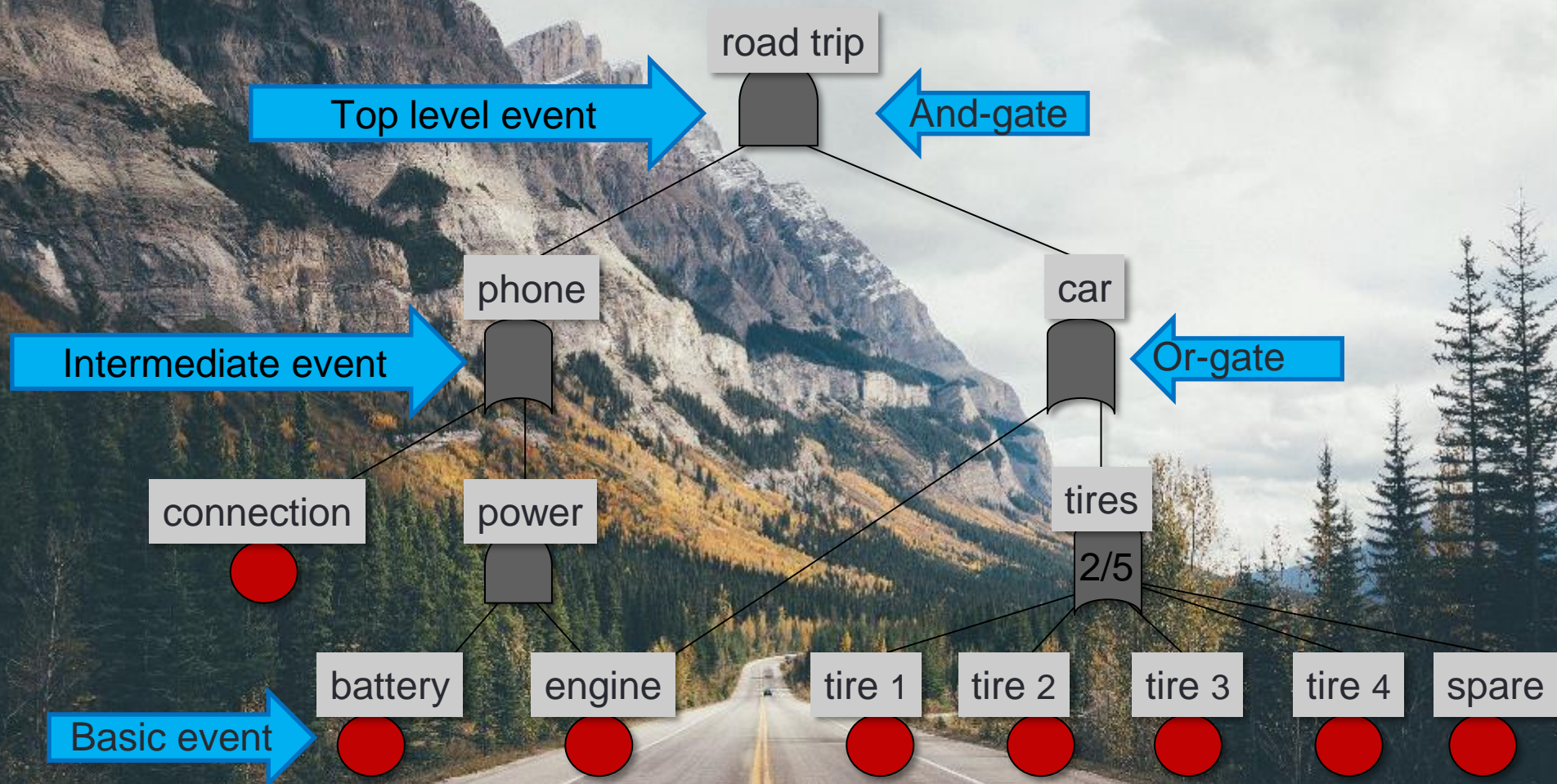
Elon Musk @elonmusk · Jun 28

There was an overpressure event in the upper stage liquid oxygen tank. Data suggests counterintuitive cause.

↩️ ↻️ 4.3K ⭐ 3.3K 👤 ⋮



# Example: Safe road trip



**Cut sets:** Which BEs make FT fail?

{battery, engine, tire 1, spare}

{connection, tire 1, spare} **minimal cut set**

{connection, engine} **minimal cut set**



# Fault tree (definition)

## A fault tree is:

- A directed, acyclic graph (not always a tree!)
- Nonleaves (*intermediate* events) are AND/OR-gates
- Leaves are called *basic events*

## Cut set

- Subset of BEs that make the FT fail

## Minimal cut sets

- Cut set that is minimal, i.e., no BE can be removed
- This is *not* the same as 'smallest cut set'!



# (Minimal) cut sets: **why do we care?**

1. **Validation of FTs**
  - If all BEs in the cut set fail, does the system fail?
  - Aka: “is this correct?”
2. **Identification of weak points**
  - Cut sets too small
  - 1 element CS = single point of failure
  - Ask the experts
3. **Common cause failures**
  - Do elements in a CS have a common cause?
4. **Risk prioritization**
  - Via cut set metrics (next slide)
5. **Calculating failure probability**
  - Later today



# Risk prioritization: cut set metrics

## Metrics

- How important is a cut set?
- How important is a basic event?

## Cut set metrics

### ■ Order

- Number of cut set elements
- Low order = more vulnerable

### ■ Frequency of basic event $e$

- How many minimal cut sets contain  $e$ ?
- High frequency =  $e$  has large impact on safety

### ■ Probability

- Product of BE probabilities
- $p_1 p_2 \dots p_n$  if BE  $e_i$  has probability  $p_i$

Min cut set	prob
connection, engine	$p_{\text{con}} * p_{\text{eng}}$
battery, engine	$p_{\text{bat}} * p_{\text{eng}}$
connection, t1, t2	$p_{\text{con}} * p_{\text{tire}}^2$
connection, t1, t3	$p_{\text{con}} * p_{\text{tire}}^2$
connection, t1, t4	$p_{\text{con}} * p_{\text{tire}}^2$
connection, t1, spare	$p_{\text{con}} * p_{\text{tire}}^2$
connection, t2, t3	$p_{\text{con}} * p_{\text{tire}}^2$
connection, t2, t4	$p_{\text{con}} * p_{\text{tire}}^2$
connection, t2, spare	$p_{\text{con}} * p_{\text{tire}}^2$
connection, t3, t4	$p_{\text{con}} * p_{\text{tire}}^2$
connection, t3, spare	$p_{\text{con}} * p_{\text{tire}}^2$
connection, t4, spare	$p_{\text{con}} * p_{\text{tire}}^2$

# Fault trees pros and cons

## Advantages

- Graphical = easy to explain and understand
- Compositional = easy to incorporate expert input
- Detailed analysis (cut sets, probability)

## Disadvantages

- Impact is binary
- Relation between events is binary
- Probabilistic analysis requires accurate statistics



# The fault trees: structure function

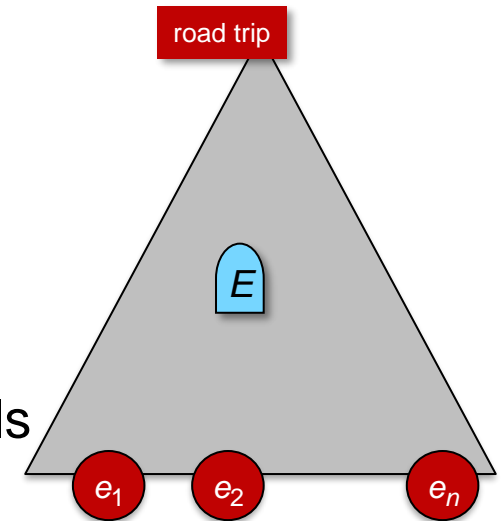
**Structure function**  $\Phi_F: \{0,1\}^{\#BEs} \rightarrow \{0,1\}$

**1** = fail; **0** = operational

- Given values  $e_1, \dots, e_n$ ,  $\Phi_F(\vec{e})$  tells whether  $F$  fails

**Extension:**  $\Phi_F: \{0,1\}^{\#BEs} \times \text{Elt} \rightarrow \{0,1\}$

- Given values  $e_1, \dots, e_n$ ,  $\Phi_F(\vec{e}, E)$  tells whether element  $E$  fails



## Recursive definition

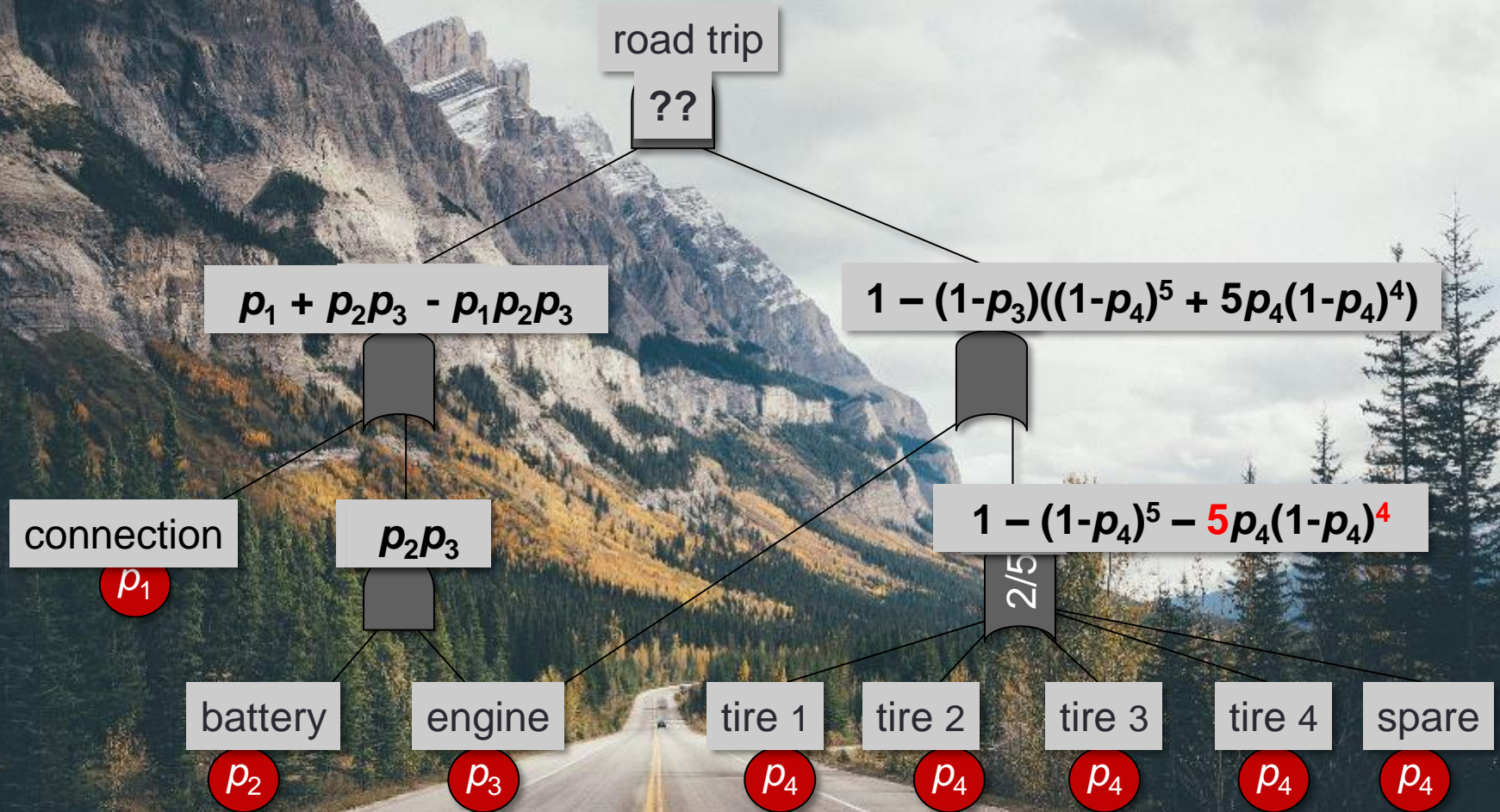
- If  $E$  is an AND-gate:  $\Phi_F(\vec{e}, E) = 1$  iff  $\Phi_F(\vec{e}, E') = 1$  for all children  $E'$  of  $E$
- If  $E$  is an OR-gate:  $\Phi_F(\vec{e}, E) = 1$  iff  $\Phi_F(\vec{e}, E') = 1$  for some child  $E'$  of  $E$
- ...etc...

## Unreliability / Failure probability

Suppose  $p_i = \mathbf{P}(e_i = 1)$  are known and are *independent*

Then  $U(F) = \mathbf{P}(\Phi_F(\vec{e}, \text{top}) = 1)$ .

# Question: determine unreliability / failure probability



$$P[A \wedge B] = P[A] P[B], \quad A, B \text{ indep}$$

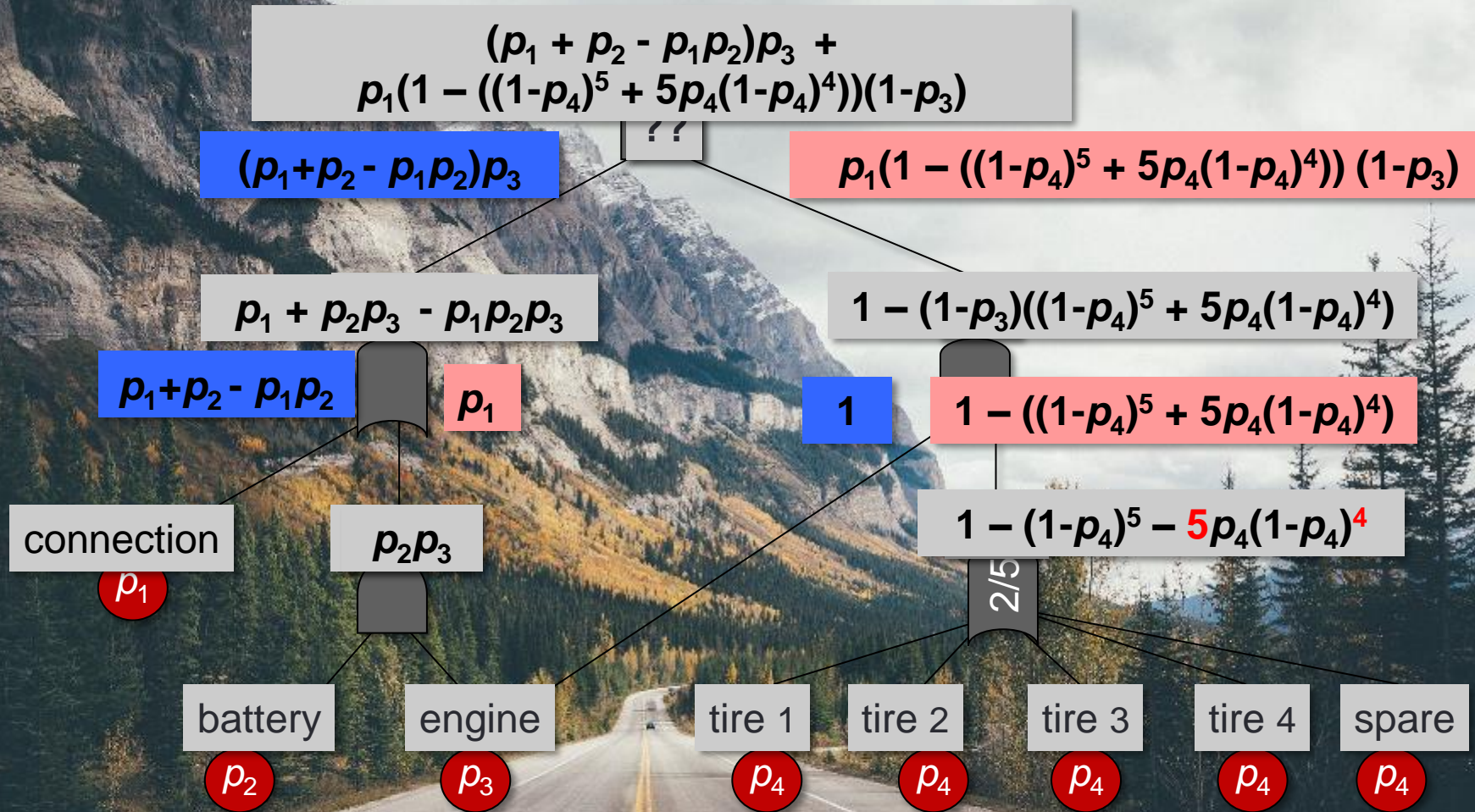
$$P[0 \text{ tires fail}] = (1-p_4)^5$$

$$P[1 \text{ tire fails}] = 5p_4(1-p_4)^4$$

$$P[A \vee B] = P[A] + P[B] - P[A \wedge B] \\ = 1 - (1-P[A])(1-P[B])$$

$$P[B^c] = 1 - P[B]$$

# Question: determine unreliability / failure probability



Case 1: engine fails;  $p_3=1$

Case 2: engine does not fail;  $p_3=0$

$$P[A] = P[A|B]P[B] + P[A|B^c] P[B^c]$$

# Simplify the computation

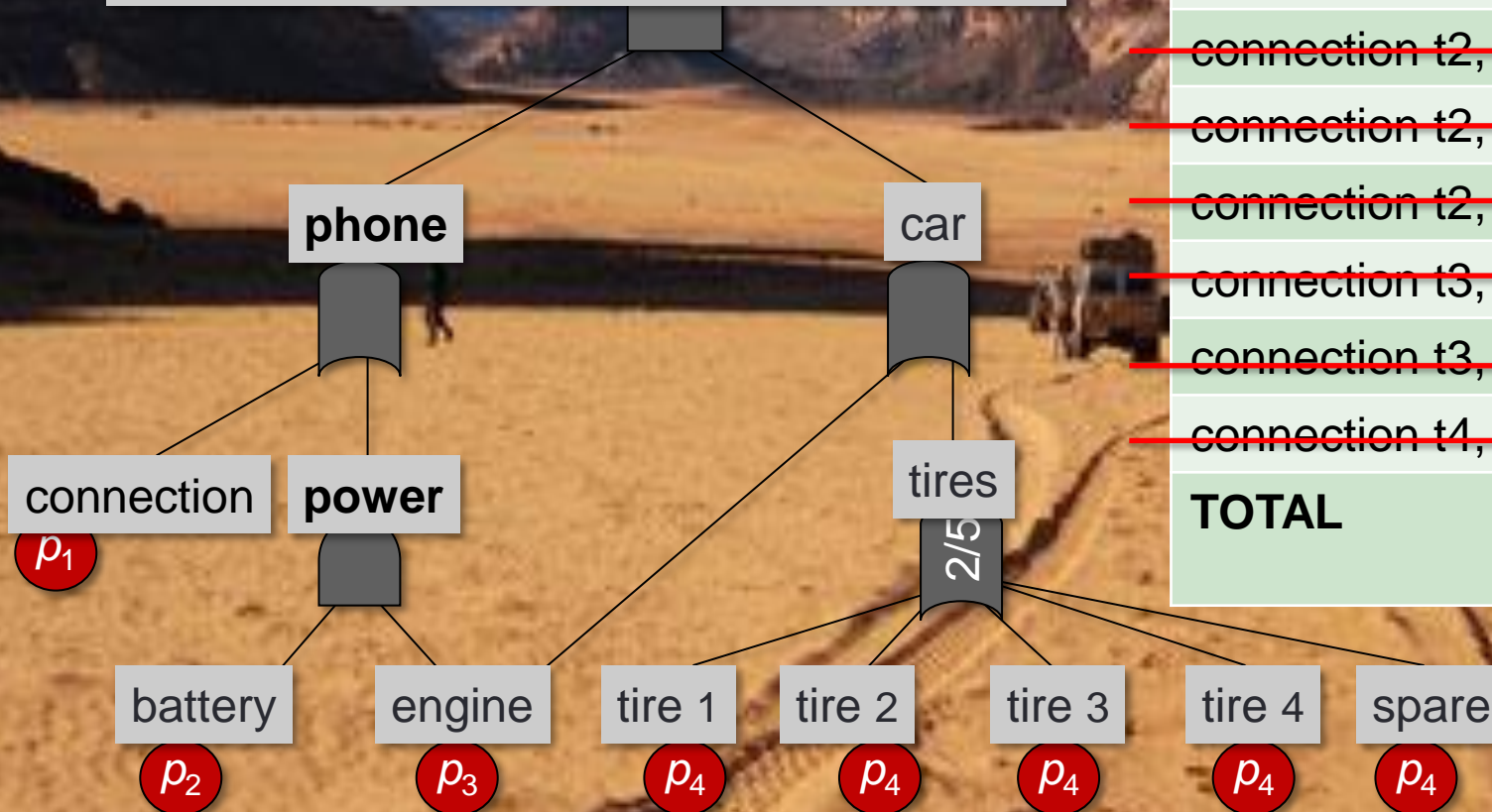
Find 3 ways to speed up this computation

1. Use minimal cut sets
2. Disregard extremely small probabilities
3. Use BDDs



# Speed up: Using cut sets

$$(p_1 + p_2 - p_1 p_2) p_3 + p_1 (1 - ((1 - p_4)^5 + 5 p_4 (1 - p_4)^4) (1 - p_3))$$



Min cut set	prob
connection, engine	$p_1 * p_3$
battery, engine	$p_2 * p_3$
<del>connection, t1, t2</del>	<del><math>p_1 * p_4^2</math></del>
<del>connection, t1, t3</del>	<del><math>p_1 * p_4^2</math></del>
<del>connection t1, t4</del>	<del><math>p_1 * p_4^2</math></del>
<del>connection t1, spare</del>	<del><math>p_1 * p_4^2</math></del>
<del>connection t2, t3</del>	<del><math>p_1 * p_4^2</math></del>
<del>connection t2, t4</del>	<del><math>p_1 * p_4^2</math></del>
<del>connection t2, spare</del>	<del><math>p_1 * p_4^2</math></del>
<del>connection t3, t4</del>	<del><math>p_1 * p_4^2</math></del>
<del>connection t3, spare</del>	<del><math>p_1 * p_4^2</math></del>
<del>connection t4, spare</del>	<del><math>p_1 * p_4^2</math></del>
<b>TOTAL</b>	$p_1 * p_3 + p_2 * p_3 + 10 * p_1 * p_4^2$

Note:  $p_1, p_4$  should be low

## Speed up 4: Using BDDs

### Binary Decision Diagrams (BDDs)

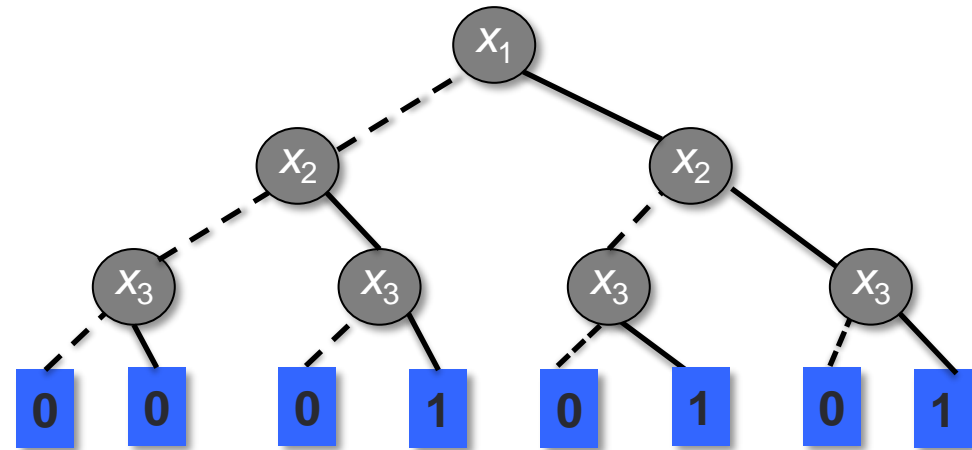
- Compact representation for Boolean functions  $f(x_1, x_2, \dots, x_n)$ 
  - e.g. the [structure function](#) of a FT
- Heavily used in model checking
  - state space
- **NOT** Behaviour-driven development! (testing)

# Example: $(x_1 \vee x_2) \wedge x_3$

Truth Table

$x_1$	$x_2$	$x_3$	$f(x_1, x_2, x_3)$
0	0	0	0
0	0	1	0
0	1	0	0
0	1	1	1
1	0	0	0
1	0	1	1
1	1	0	0
1	1	1	1

Decision Tree

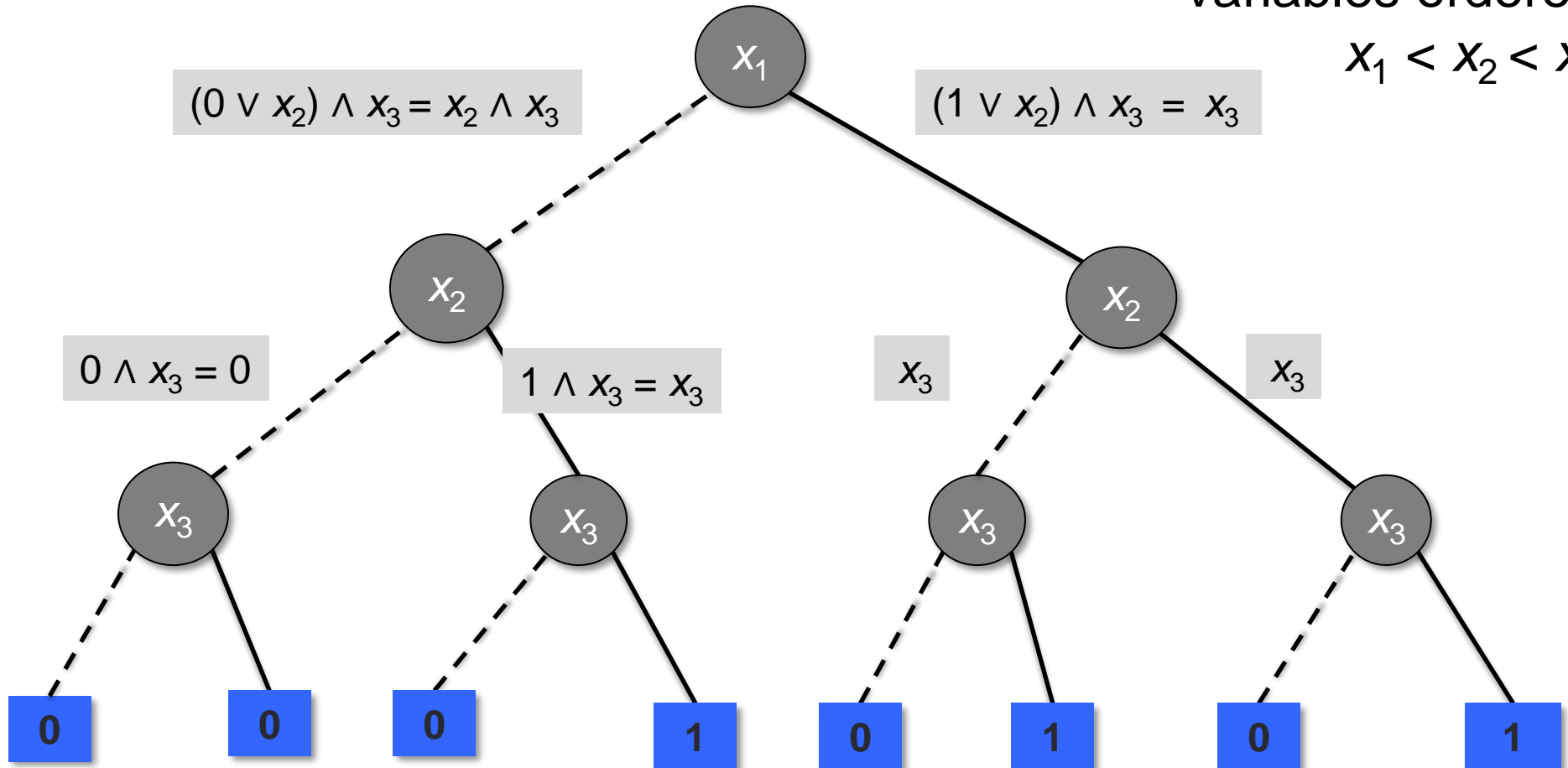


- Vertex represents decision
- Follow dashed line for value 0
- Follow solid line for value 1
- Function value in leaf

# Deriving the BDD: $(x_1 \vee x_2) \wedge x_3$

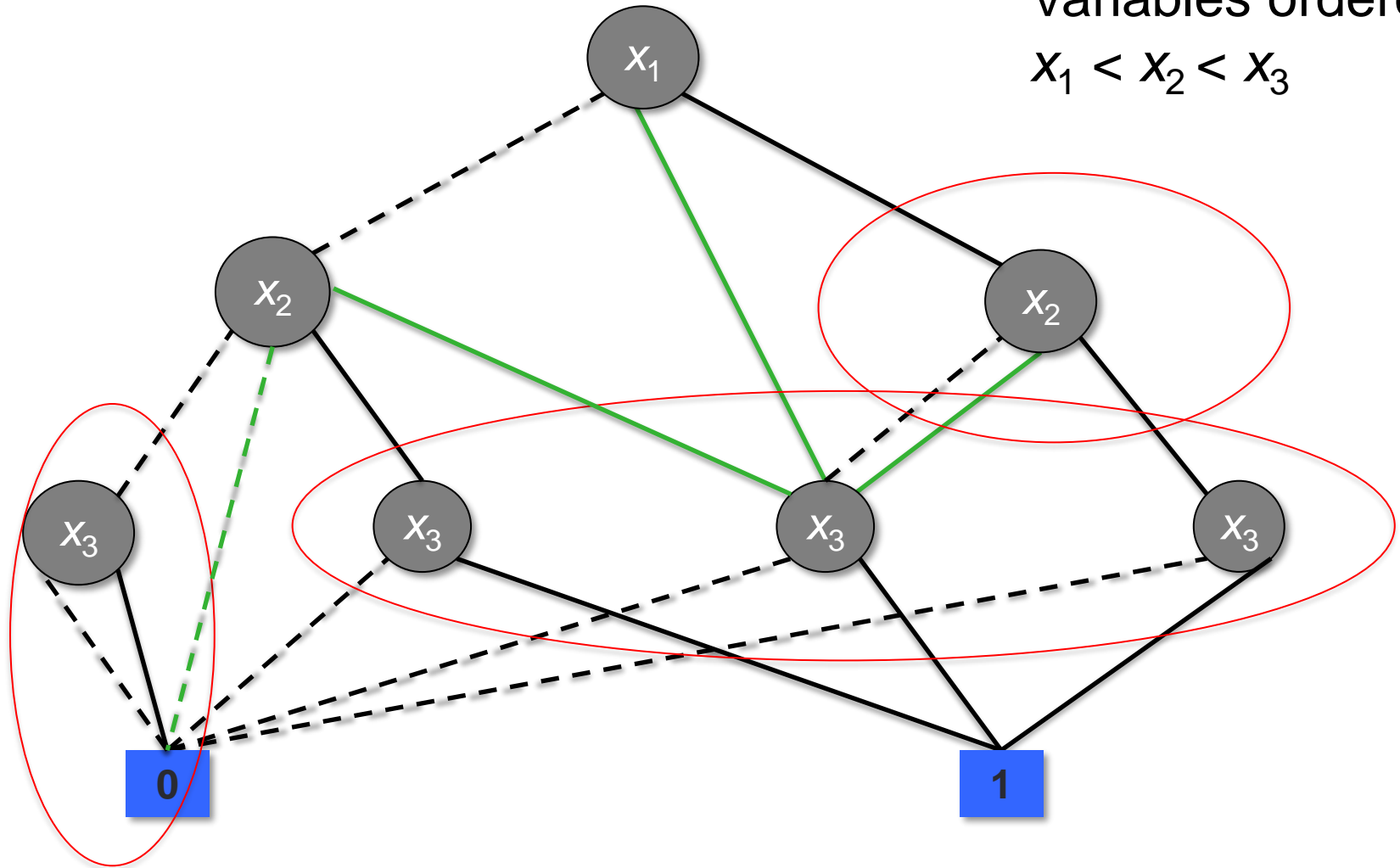
Variables ordered

$x_1 < x_2 < x_3$

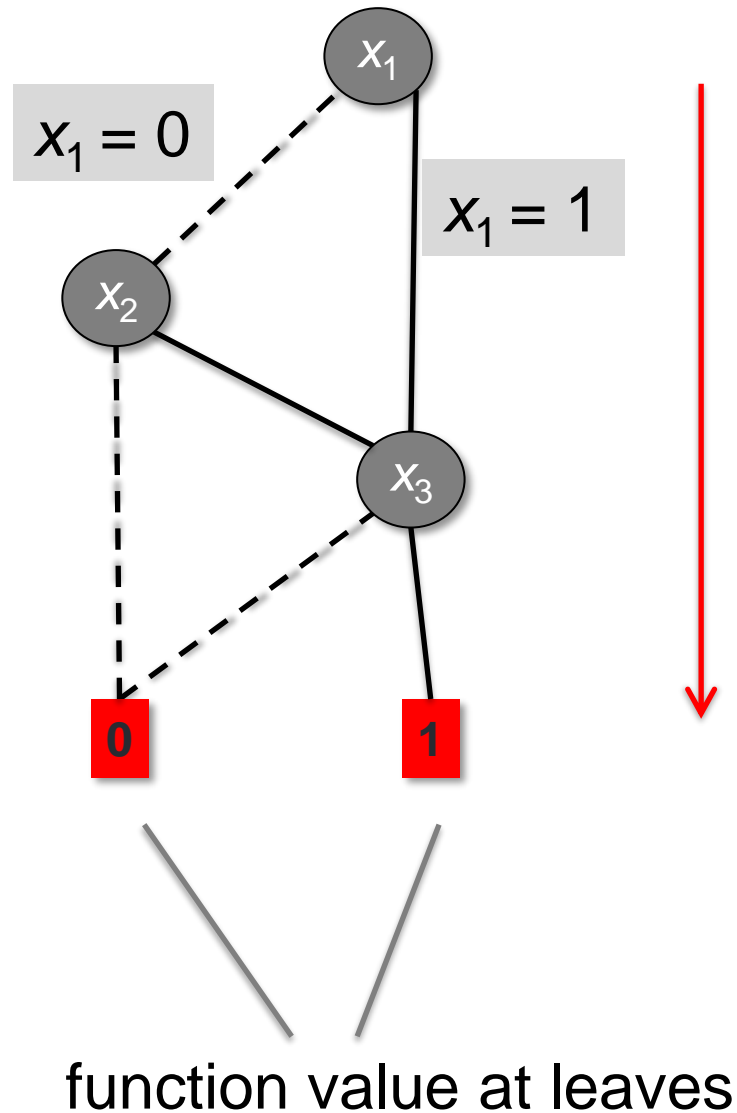


# Reducing the BDD: $(x_1 \vee x_2) \wedge x_3$

Variables ordered  
 $x_1 < x_2 < x_3$



**Example:**  $(x_1 \vee x_2) \wedge x_3$



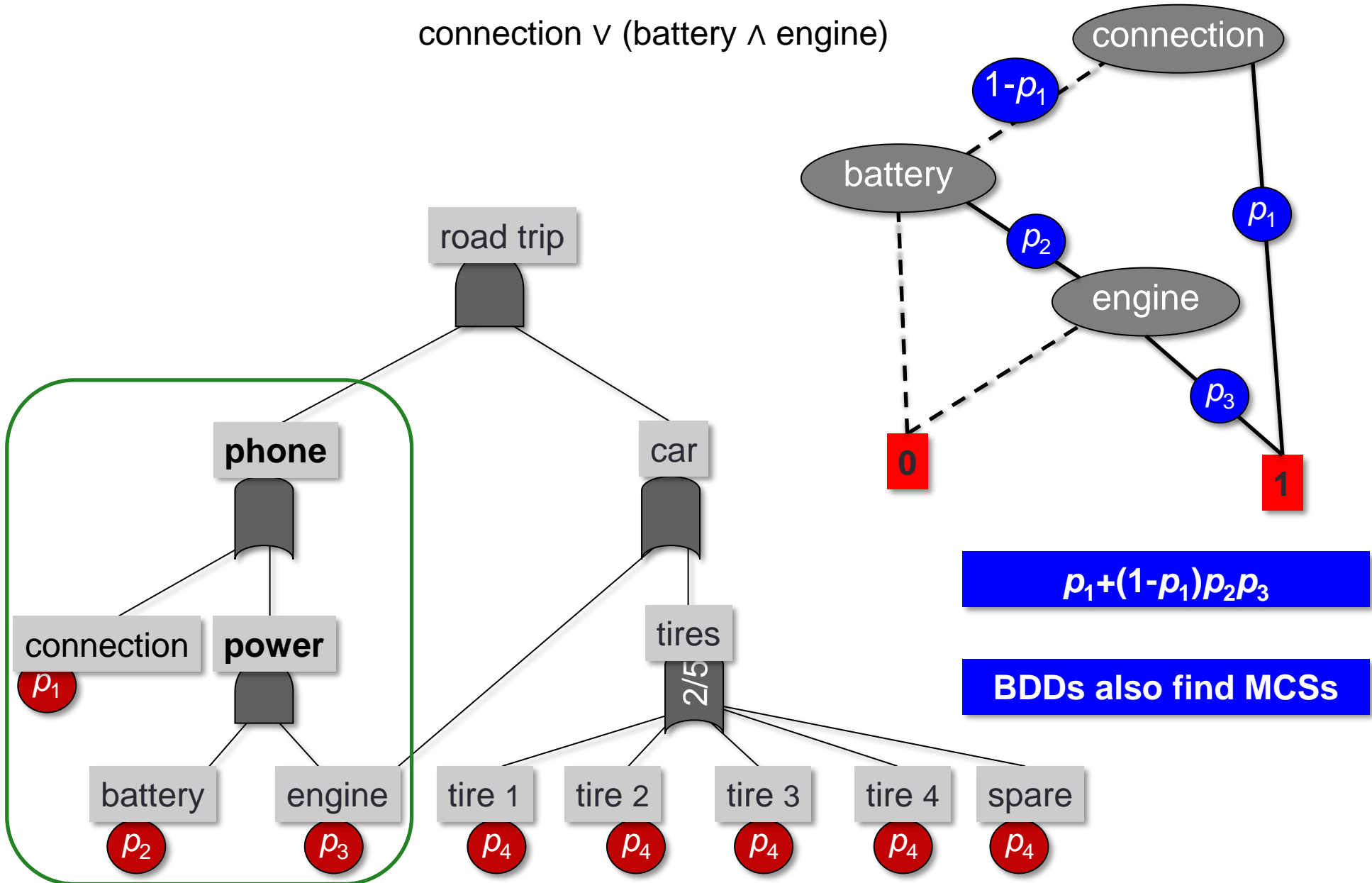
Variables ordered

$x_1 < x_2 < \dots < x_n$

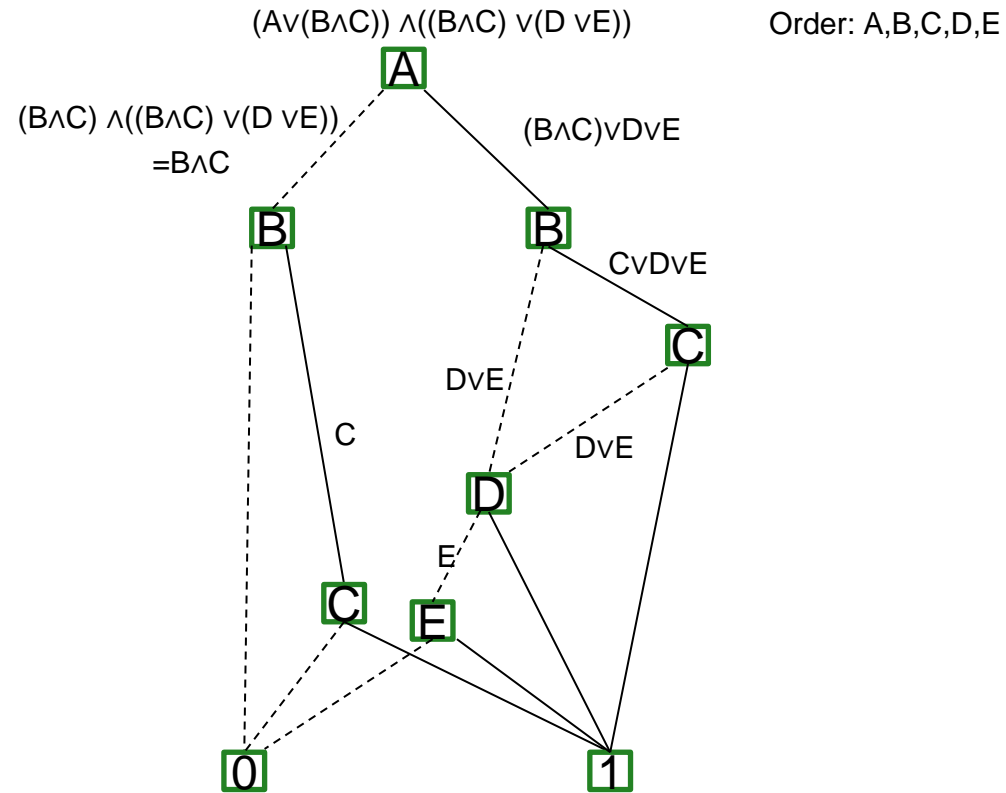
- Size of BDDs heavily depends on variable order  
 $x_1 < x_2 < \dots < x_n$
- Finding best order is NP-hard
- Good algos in practice

# Using BDDs

connection  $\vee$  (battery  $\wedge$  engine)



# Reduced BDDs from scratch



# Calculating unreliability/failure probability: summary

## 1. Via MCS

- (slight) overapproximation

## 2. Bottom-up

- Fast; only correct if FT is actually a tree

## 3. Via BDDs

- Worst-case exponential size, ok in practice



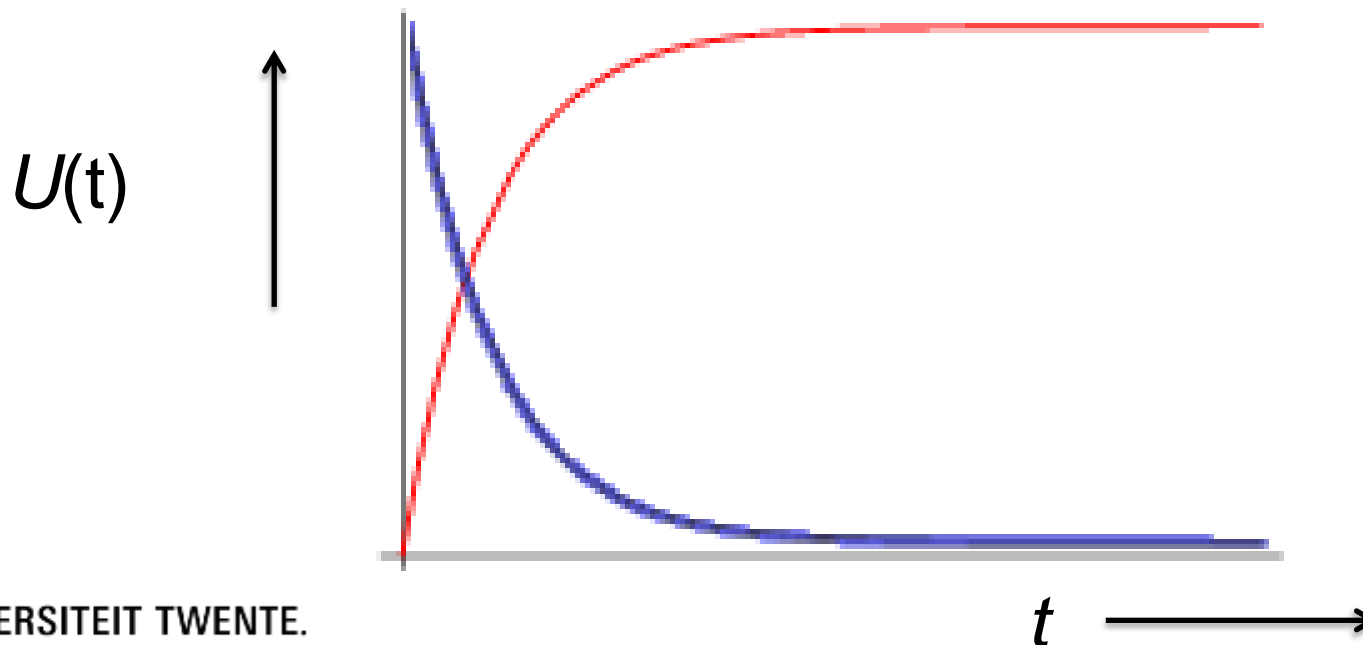
# Unreliability over time

- Unreliability

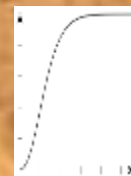
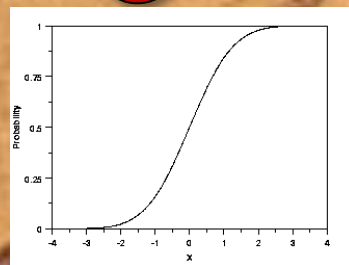
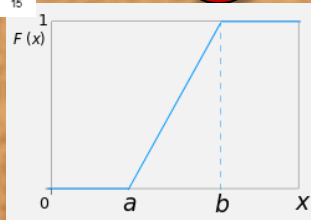
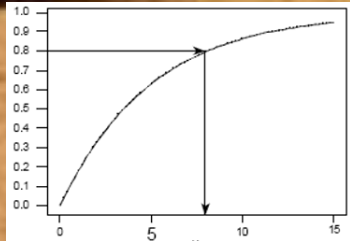
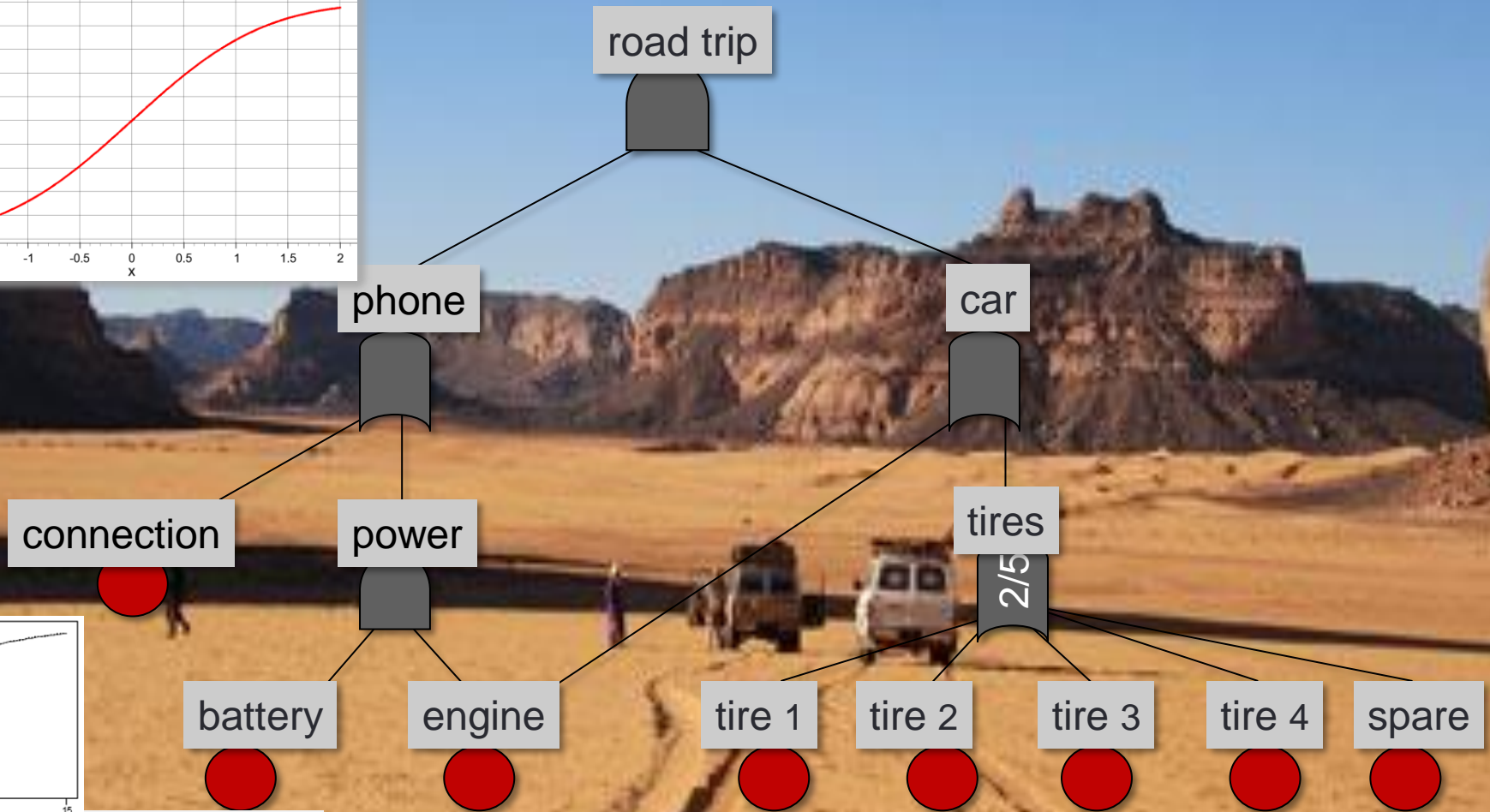
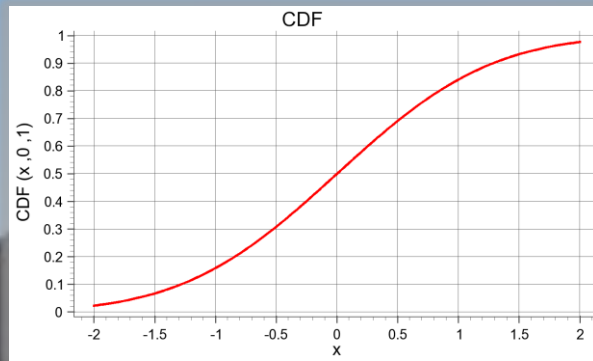
$$U(t) = \mathbf{P}[\text{failure before time } t]$$

- Reliability / Survivor function

$$\begin{aligned} R(t) &= \mathbf{P}[\text{no failure until time } t] \\ &= 1 - U(t) \end{aligned}$$

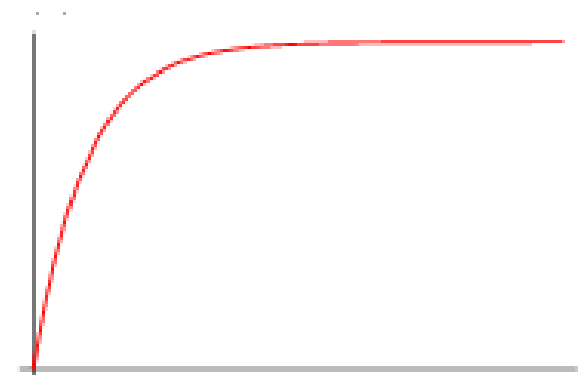
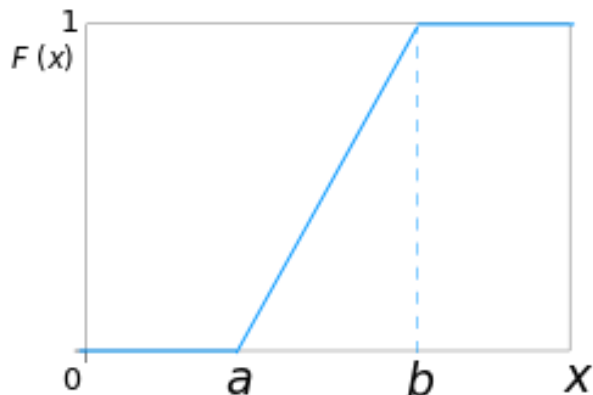


# Continuous probability: failure behaviour over time

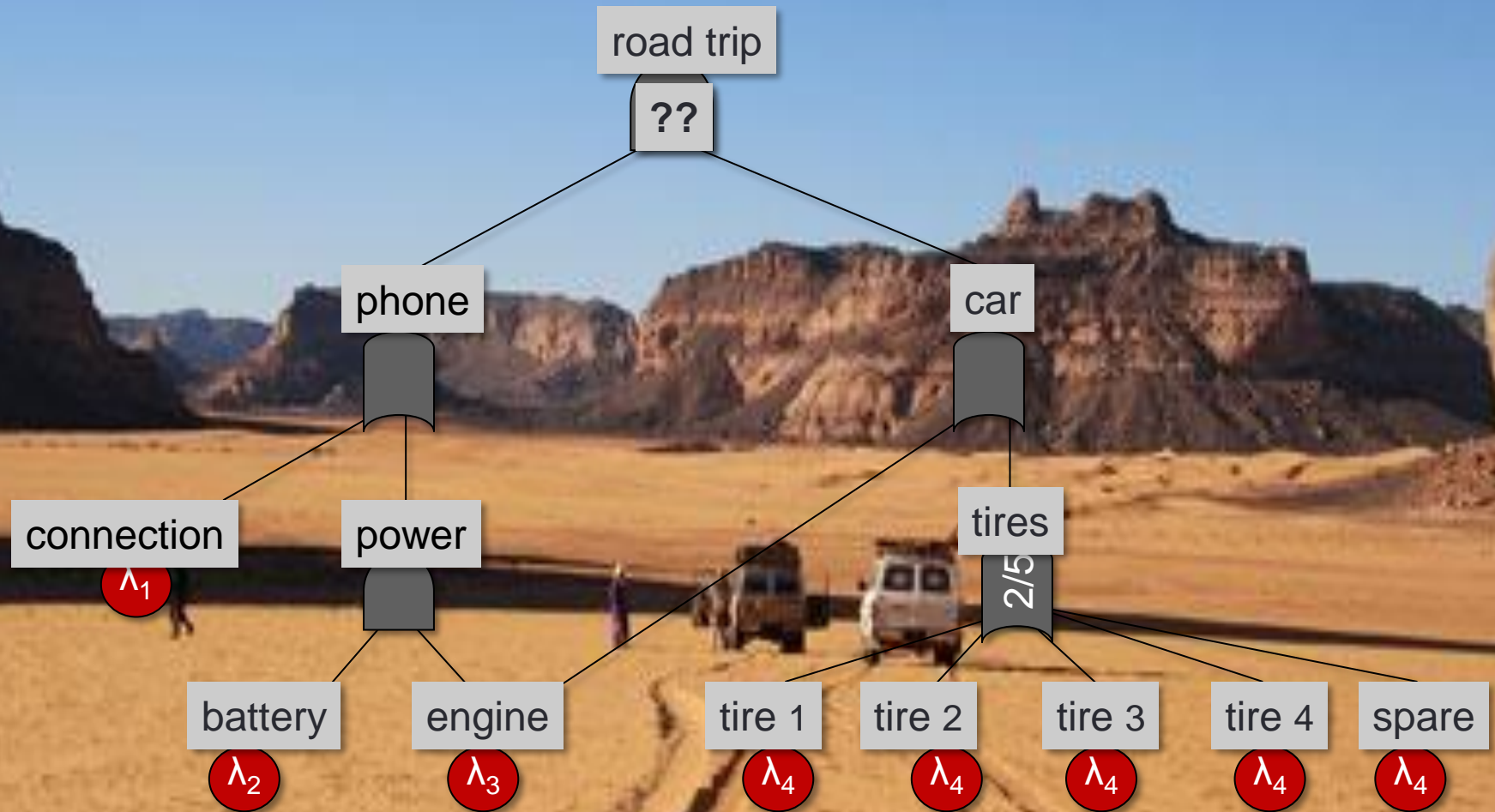


# Continuous probability distributions: which one?

- **Uniform distribution**
- **Gaussian**
- **Exponential**
  - realistic model for degradation
  - mathematically tractable
  - approximation via composed exponentials
- **Weibull**
  - generalized exponential
  - often used
  - not discussed
- Use the cumulative density function:
  - $F(x) = \mathbf{P}[X \leq x]$

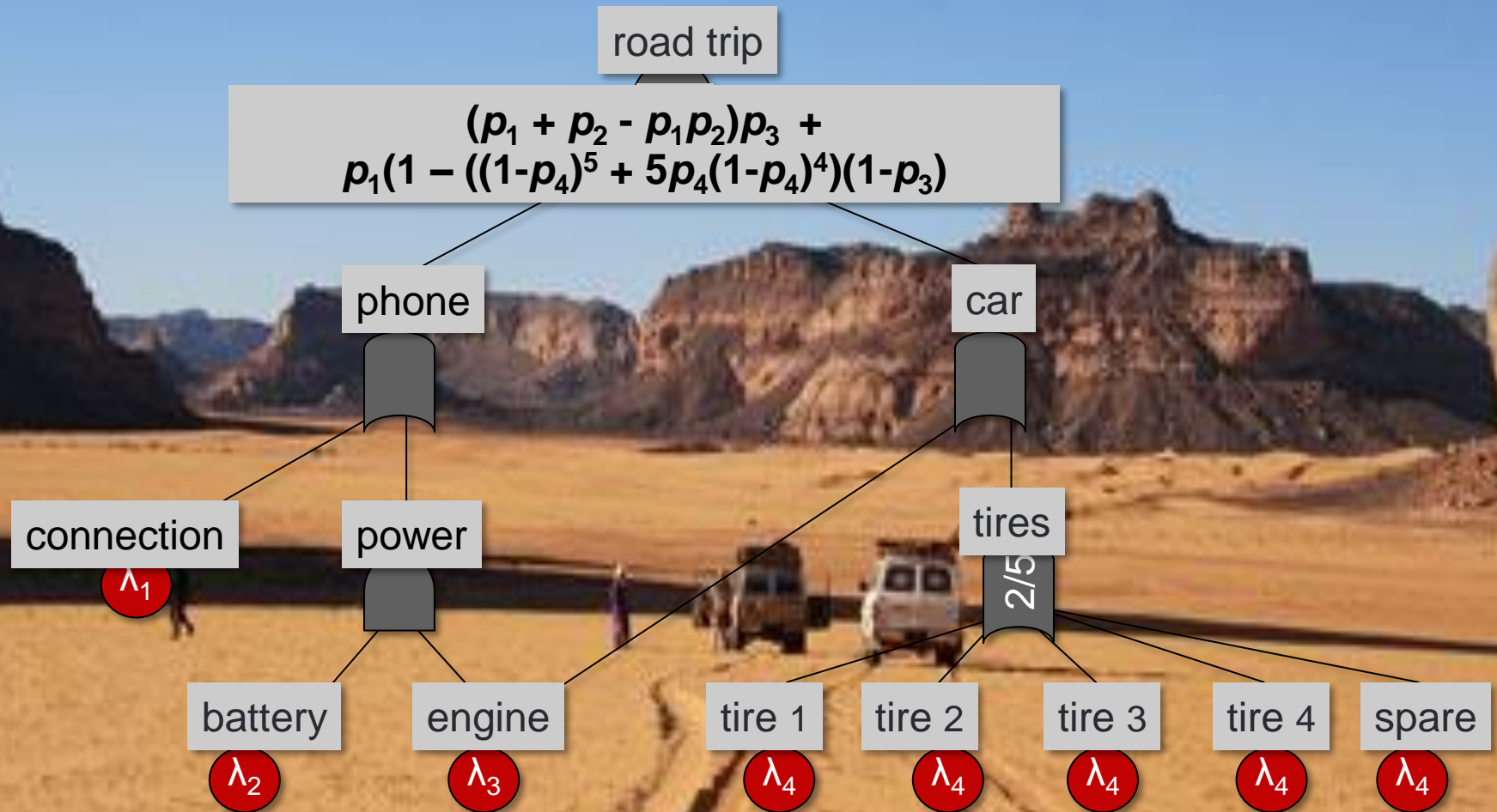


# Example: probabilistic analysis



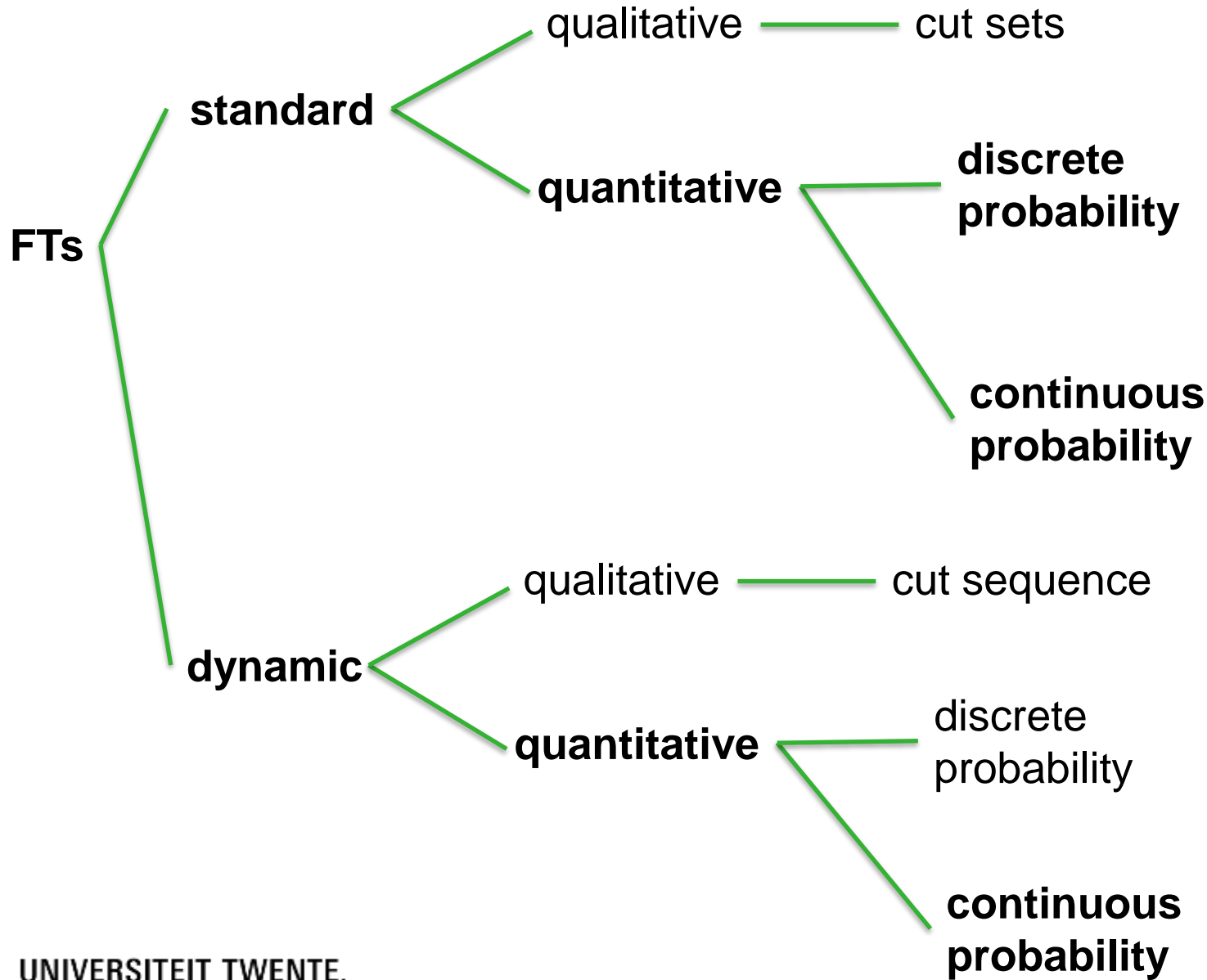
$$p_i(t) = \mathbf{P}[\text{BE } i \text{ fails before time } t] = 1 - e^{-\lambda_i * t}$$

# Example: probabilistic analysis



- $p_1(t)$  varies over time
- $p_1(t)$  probability of having failed at time  $t$
- Substitute  $p_1(t) = 1 - e^{-\lambda_1 t}$
- ... works the same for other probability distributions

# Overview



## Technique

- Recursive
- BDDs

## Technique

- Bottom up
- Cut sets
- BDDs

## Technique

- The same!

## Technique

- Model checking
- Next time

**Next week: BREAK!**



# In 2 weeks: dynamic fault trees

- FTs with more complicated gate types
- More time-dependent behaviour
- Analysis using Markov chains

## Tomorrow: tutorial

- Work on next homework set
- Work on additional exercises

