

Course : **Model Reduction**

Date : April 14, 2025

Time : 13:45-15:45

Motivate all answers and calculations.

The use of electronic devices and/or lecture notes is not permitted.

- [2p] 1. Consider the standard state space equation

$$\dot{x}(t) = Ax(t).$$

We assume that  $A = JH$ , with  $J^* = -J$ ,  $H^* = H$ , and  $H$  is a (strictly) positive matrix, i.e.  $x^*Hx > 0$  whenever  $x \neq 0$ .

Show that all eigenvalues of  $A$  lie on the imaginary axis.

**Hint:** Consider  $x^*HAx$ .

- [1.5p] 2. Consider the standard state space system

$$\dot{x}(t) = Ax(t) + Bu(t), \quad y(t) = Cx(t) \quad (1)$$

for which we assume that the input and output take values in  $\mathbb{C}$ . Its transfer function is denoted by  $G(s)$ . Suppose that along solutions of (1) the following holds

$$\|x(t)\|^2 \leq \operatorname{Re}(u(t)y(t)).$$

Show that  $\operatorname{Re}(G(s)) \geq 0$  whenever  $\operatorname{Re}(s) > 0$ .

- [1.5p] 3. Given a state space system with observability and controllability gramians given by

$$P = \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix}, \quad Q = \begin{bmatrix} 8 & 1 \\ 1 & 4 \end{bmatrix}$$

Argue whether or not you would reduce this model.

4. Consider the Burgers equation with periodic boundary condition

$$\begin{cases} \mathcal{B}(u) \equiv u_t + (\frac{1}{2}u^2)_x - \nu u_{xx} = 0 & \text{for } x \in ]0, \pi[ , t > 0 \\ u(0, t) = u(\pi, t) = 0 & \text{for } t > 0 \\ u(x, 0) = \sin(2kx) & \text{for } x \in ]0, \pi[ \end{cases}$$

where  $\mathcal{B}$  denotes the Burgers operator,  $\nu > 0$  is a constant viscosity,  $k \in \mathbb{Z}$  the wavenumber ( $k \neq 0$ ) and  $(x, t)$  the spatial and temporal variables respectively. The top-hat filter  $L$  is a convolution filter, defined as

$$\bar{u}(x, t) \equiv L(u)(x, t) \equiv \int_{x-\Delta/2}^{x+\Delta/2} \frac{u(\xi, t)}{\Delta} d\xi,$$

where  $\Delta > 0$  denotes the filter-width.

- [1p] a) Apply the top-hat filter to  $f(x) = \sin(kx)$  and express the result as  $\bar{f}(x) = H(k\Delta)f(x)$  for suitable  $H$ . Discuss the effect of filtering for small and large  $k\Delta$ .
- [2p] b) Apply the top-hat filter to the Burgers equation and derive the unclosed equation governing the evolution of  $\bar{u}$  in the form  $\mathcal{B}(\bar{u}) = (\tau(u, \bar{u}))_x$ . Discuss the closure term  $(\tau(u, \bar{u}))_x$  for small and large scales. Motivate the steps in your derivation.
- [1p] c) A closure model  $m(\bar{u}) = C\bar{u}_x$ , with constant  $C$ , is adopted to approximate  $(\tau(u, \bar{u}))_x$ . Should  $C$  be positive or negative to enhance the decay rate of the resolved kinetic energy  $E(t) = \int_0^\pi (\bar{u}^2(\xi, t)/2) d\xi$ ?

Total: 1+5+4 points